

Another example:

$$x_1 - 7x_2 + 6x_4 = 5$$

$$x_3 - 2x_4 = -3$$

$$-x_1 + 7x_2 - 4x_3 + 7x_4 = 8$$

$$A = \begin{bmatrix} x_1 & x_2 & x_3 & x_4 \\ 1 & -7 & 0 & 6 \\ 0 & 0 & 1 & -2 \\ -1 & 7 & -4 & 2 \end{bmatrix}$$

$$b = \begin{bmatrix} 5 \\ -3 \\ 8 \end{bmatrix}$$

Augmented matrix

$$\left[A : b \right] = \left[\begin{array}{cccc|c} 1 & -7 & 0 & 6 & 5 \\ 0 & 0 & 1 & -2 & -3 \\ -1 & 7 & -4 & 2 & 8 \end{array} \right] \quad R_3 \leftarrow R_3 + R_1$$

$$\left[\begin{array}{cccc|c} 1 & -7 & 0 & 6 & 5 \\ 0 & 0 & 1 & -2 & -3 \\ 0 & 0 & -1 & 8 & 13 \end{array} \right] \quad R_3 \leftarrow R_3 + 4R_2$$

$$\rightarrow \left[\begin{array}{cccc|c} 1 & -7 & 0 & 6 & 5 \\ 0 & 0 & 1 & -2 & -3 \\ 0 & 0 & 0 & 0 & 1 \end{array} \right]$$

A ↓ alg notation

wasn't
a pivot of A
because it's
in the b
column.

$$x_1 - 7x_2 + 6x_4 = 5$$

$$x_3 - 2x_4 = -3$$

$$\theta = 1$$

contradiction
so no solutions

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Section 1.4
Theorem 4

Theorem about when $Ax = b$ has a solution.

Let A be an $m \times n$ matrix. Then the following statements are logically equivalent. That is, for a particular A , either they are all true statements or they are all false.

- ✓ a. For each \mathbf{b} in \mathbb{R}^m , the equation $Ax = \mathbf{b}$ has a solution.
- ? b. Each \mathbf{b} in \mathbb{R}^m is a linear combination of the columns of A .
- ? c. The columns of A span \mathbb{R}^m .
- ✓ d. A has a pivot position in every row.

we see from using the echelon form that if every row has a pivot then there is a solution... That's actually how we find the solution!

$$12. A = \begin{bmatrix} 1 & 2 & 1 \\ -3 & -1 & 2 \\ 0 & 5 & 3 \end{bmatrix}, \mathbf{b} = \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}$$

$$[A|b] = \left[\begin{array}{ccc|c} 1 & 2 & 1 & 0 \\ -3 & -1 & 2 & 1 \\ 0 & 5 & 3 & -1 \end{array} \right] \quad r_2 \leftarrow r_2 + 3r_1$$

$$\left[\begin{array}{ccc|c} 1 & 2 & 1 & 0 \\ 0 & 5 & 5 & 1 \\ 0 & 5 & 3 & -1 \end{array} \right] \quad r_3 \leftarrow r_3 - r_2$$

$$\left[\begin{array}{ccc|c} 1 & 2 & 1 & 0 \\ 0 & 5 & 5 & 1 \\ 0 & 0 & -2 & -2 \end{array} \right]$$

triangular form
zeros means
we have
the echelon
form

there is a pivot in every row of A .

means...

For each \mathbf{b} in \mathbb{R}^m , the equation $Ax = \mathbf{b}$ has a solution.

If $\mathbf{v}_1, \dots, \mathbf{v}_p$ are in \mathbb{R}^n , then the set of all linear combinations of $\mathbf{v}_1, \dots, \mathbf{v}_p$ is denoted by $\text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ and is called the **subset of \mathbb{R}^n spanned (or generated) by $\mathbf{v}_1, \dots, \mathbf{v}_p$** . That is, $\text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$ is the collection of all vectors that can be written in the form

$$c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \dots + c_p\mathbf{v}_p$$

with c_1, \dots, c_p scalars.

$$\text{Span}\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p\} = \left\{ c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \dots + c_p\mathbf{v}_p : c_1, c_2, \dots, c_p \in \mathbb{R} \right\}$$

$$A = \begin{bmatrix} & & & & \\ \vdots & \vdots & \vdots & \vdots & \\ \mathbf{v}_1 & \mathbf{v}_2 & \cdots & | & \mathbf{v}_p \\ \vdots & \vdots & & & \vdots \\ & & & & \end{bmatrix}$$

Column representation of matrix-vector product

$$A\mathbf{x} = \mathbf{v}_1x_1 + \mathbf{v}_2x_2 + \dots + \mathbf{v}_px_p$$

means c_1, c_2 and c_p
are real numbers
that is, scalars.

$$\text{Span}\left\{\begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ 0 \\ 0 \end{bmatrix}\right\} = \left\{ c_1 \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} + c_3 \begin{bmatrix} -1 \\ 2 \\ 0 \\ 0 \end{bmatrix} : c_1, c_2, c_3 \in \mathbb{R} \right\}$$

$$A = \begin{bmatrix} & x_1 & x_2 & x_3 \\ 1 & 1 & 0 & -1 \\ 2 & 0 & 2 & 2 \\ 3 & 1 & 1 & 0 \\ 4 & 0 & 0 & 0 \end{bmatrix}$$

What linear function does A correspond to?

$$f(\mathbf{x}) = A\mathbf{x} = \begin{bmatrix} x_1 + x_2 - x_3 \\ 2x_1 + 0x_2 + 2x_3 \\ 3x_1 + x_2 + 0x_3 \\ 4x_1 + 0x_2 + 0x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}x_1 + \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}x_2 + \begin{bmatrix} -1 \\ 2 \\ 0 \\ 0 \end{bmatrix}x_3$$

$$\text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_p\} = \{A\mathbf{x} : \mathbf{x} \in \mathbb{R}^p\} \quad \text{where } A = \begin{bmatrix} & & & \\ \vdots & \vdots & \vdots & \\ \mathbf{v}_1 & \mathbf{v}_2 & \cdots & | & \mathbf{v}_p \\ \vdots & \vdots & & & \vdots \\ & & & & \end{bmatrix}$$

$\Rightarrow \text{range } f = \text{Col } A$

So there's lots of different notation that all means the same thing

$$f(x) = Ax = \begin{bmatrix} x_1 + x_2 - x_3 \\ 2x_1 + 0x_2 + 2x_3 \\ 3x_1 + x_2 + 0x_3 \\ 4x_1 + 0x_2 + 0x_3 \end{bmatrix}$$

$$f\left(\begin{bmatrix} 5 \\ 6 \\ 7 \end{bmatrix}\right) = \begin{bmatrix} 1 & 1 & -1 \\ 2 & 0 & 2 \\ 3 & 1 & 0 \\ 4 & 0 & 0 \end{bmatrix} \begin{bmatrix} 5 \\ 6 \\ 7 \end{bmatrix}$$

$$= \begin{bmatrix} x_1 + x_2 - x_3 \\ 2x_1 + 0x_2 + 2x_3 \\ 3x_1 + x_2 + 0x_3 \\ 4x_1 + 0x_2 + 0x_3 \end{bmatrix} = \begin{bmatrix} \text{dot products} \\ 1 \cdot 5 + 1 \cdot 6 + (-1) \cdot 7 \\ 2 \cdot 5 + 0 \cdot 6 + 2 \cdot 7 \\ 3 \cdot 5 + 1 \cdot 6 + 0 \cdot 7 \\ 4 \cdot 5 + 0 \cdot 6 + 0 \cdot 7 \end{bmatrix}$$

$$(x_1, x_2, x_3) = (5, 6, 7)$$

between
the rows of
the matrix
and x .

In general if A has m rows like

$$A = \begin{bmatrix} a_1 \\ \vdots \\ a_2 \\ \vdots \\ a_m \end{bmatrix}$$

then

$$Ax = \begin{bmatrix} a_1 \cdot x \\ a_2 \cdot x \\ \vdots \\ a_m \cdot x \end{bmatrix}$$

dot products of the vector a_i with x .

row representation of matrix-vector products.

Column representation of matrix-vector product

$$Ax = v_1x_1 + v_2x_2 + \dots + v_px_p$$

rows
columns

Definition of the Nullspace of a matrix $A \in \mathbb{R}^{m \times n}$

$$\text{Nul } A = \{x \in \mathbb{R}^n : Ax = 0\}.$$

\in means A has m rows and n columns

- Connect this to the free variables next time...