

Matrix factorizations

Define matrix multiplication as the matrix corresponding to the composition of functions.

$$A \in \mathbb{R}^{n \times n}$$
$$f: \mathbb{R}^n \rightarrow \mathbb{R}^n$$
$$f(x) = Ax$$

$$B \in \mathbb{R}^{n \times n}$$
$$g: \mathbb{R}^n \rightarrow \mathbb{R}^n$$
$$g(x) = Bx$$

We know $f \circ g$ is a linear function since f and g were linear, so there is a matrix $C \in \mathbb{R}^{n \times n}$ such that

$$(f \circ g)(x) = Cx$$

we define matrix multiplication so $C = AB$.

what is C ?

$$(f \circ g)(x) = f(g(x)) = f(Bx) = A(Bx) = Cx = (AB)x$$

Note finding C is complicated. If you just want to plug one vector in to $(f \circ g)(x)$ its easier to compute

$$w = Bx \text{ and then } (f \circ g)(x) = Aw$$

using two matrix-vector multiplications.

How difficult is it to find C ?

$$C = \begin{bmatrix} (f \circ g)(e_1) & \vdots & (f \circ g)(e_2) & \vdots & \dots & \vdots & (f \circ g)(e_n) & \vdots \\ \vdots & & \vdots & & & & \vdots & \end{bmatrix}$$

$$(f \circ g)(e_i) = f(g(e_i)) = A(Be_i)$$

using a matrix-vector multiplication n times...

Suppose we wanted to compute $(f \circ g)(x)$ for m different x 's

find C and then compute Cx for m different x 's.

n + m matrix vector mult.

Simply compute $A(Bx)$ for m different x 's
 $\underbrace{\quad\quad}_{2m}$ matrix vector mult

When is

$$n + m < 2m$$

$$n < m$$

So if there are more than n inputs x 's then it's better to precompute C . Otherwise not.

If you can multiply matrices, you can then think about Gaussian elimination.

$$[A | e_1; e_2] = \left[\begin{array}{cc|cc} 1 & 2 & 1 & 0 \\ 3 & 4 & 0 & 1 \end{array} \right]$$

echelon

$$\left[\begin{array}{cc|cc} 1 & 2 & 1 & 0 \\ 0 & -2 & -3 & 1 \end{array} \right]$$

$$\left[\begin{array}{cc|cc} 1 & 0 & -2 & 1 \\ 0 & -2 & -3 & 1 \end{array} \right]$$

$$\left[\begin{array}{cc|cc} 1 & 0 & -2 & 1 \\ 0 & 1 & 3/2 & -1/2 \end{array} \right]$$

$$\underbrace{r_2 \leftarrow r_2 - 3r_1}_{\text{mult by a matrix}} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = [r_2 \leftarrow r_2 - 3r_1]$$

$$\underbrace{r_1 \leftarrow r_1 + r_2}_{\text{multiplication by}} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = E_1$$

$$\underbrace{r_2 \leftarrow -\frac{1}{2}r_2}_{\text{multiplication by}} [r_1 \leftarrow r_1 + r_2] = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = E_2$$

$$[r_2 \leftarrow -\frac{1}{2}r_2] = \begin{bmatrix} 1 & 0 \\ 0 & -1/2 \end{bmatrix} = E_3$$

Therefore. $A^{-1} = \begin{bmatrix} -2 & 1 \\ 3/2 & -1/2 \end{bmatrix}$

mult these matrices ...

$$\begin{bmatrix} 1 & 0 \\ -3 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & : & 1 & 0 \\ 3 & 4 & ; & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 & : & 1 & 0 \\ 0 & -2 & : & -3 & 1 \end{bmatrix}$$

$[r_2 \leftarrow r_2 - 3r_1]$ $[A | I] = [u | ?]$ from before

work for
matrix
matrix
mult...

$$\begin{bmatrix} 1 & 2 & : & 1 & 0 \\ 3 & 4 & ; & 0 & 1 \end{bmatrix}$$

more here.

$$\begin{bmatrix} 1 & 2 & : & 1 & 0 \\ 0 & -2 & ; & -3 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 \\ -3 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & : & 1 & 0 \\ 0 & -2 & : & -3 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 \\ -3 & 1 \end{bmatrix}^{-1} = [r_2 \leftarrow r_2 - 3r_1]^{-1} = [r_2 \leftarrow r_2 + 3r_1] = \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix}$$

Check the inverse

$$AA^{-1} = I \quad \text{for } A \in \mathbb{R}^{n \times n}$$

$$A^{-1}A = I$$

$$\begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 \\ -3 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

This is the identity..

inverse over here.

$$\cancel{\begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix}} \cancel{\begin{bmatrix} 1 & 0 \\ -3 & 1 \end{bmatrix}} \begin{bmatrix} 1 & 2 & : & 1 & 0 \\ 3 & 4 & ; & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & : & 1 & 0 \\ 0 & -2 & : & -3 & 1 \end{bmatrix}$$

Therefore, I've factored the augmented matrix as ...

$$\begin{bmatrix} 1 & 2 & : & 1 & 0 \\ 3 & 4 & ; & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & : & 1 & 0 \\ 0 & -2 & : & -3 & 1 \end{bmatrix}$$

Also

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} = \underbrace{\begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix}}_L \underbrace{\begin{bmatrix} 1 & 2 \\ 0 & -2 \end{bmatrix}}_U$$

$$A =$$

These matrices are called triangular... and the idea is triangular matrices are simpler than the original.

Note could factor A more using the other row operations...

Transposes and inverses.

Let $A \in \mathbb{R}^{n \times n}$ and pivot in every row (so invertible).

$$u = Ax \quad \text{so} \quad x = A^{-1}u$$

$$x \cdot y = A^{-1}u \cdot y = u \cdot (A^{-1})^T y = Ax \cdot (A^{-1})^T y = x \cdot A^T (A^{-1})^T y$$

Therefore

$$x \cdot Iy = x \cdot A^T (A^{-1})^T y \quad \text{for all } x, y \in \mathbb{R}^n$$

Hence

$$A^T (A^{-1})^T = I$$

which means $(A^T)^{-1} = (A^{-1})^T$.