

$$\text{row } A = \text{col } A^T$$

$$\begin{bmatrix} -2 & 4 & -2 & -4 \\ 2 & -6 & -3 & 1 \\ -3 & 8 & 2 & -3 \end{bmatrix}^T = \begin{bmatrix} -2 & 2 & -3 \\ 4 & -6 & 8 \\ -2 & -3 & 2 \\ -4 & 1 & -3 \end{bmatrix}$$

$$\begin{aligned} r_2 &\leftarrow r_2 + 2r_1 \\ r_3 &\leftarrow r_3 - r_1 \\ r_4 &\leftarrow r_4 - 2r_1 \end{aligned}$$

$$\begin{bmatrix} -2 & 2 & -3 \\ 0 & -2 & 2 \\ 0 & -5 & 5 \\ 0 & -3 & 3 \end{bmatrix}$$

$$r_3 \leftarrow r_3 - \frac{5}{2}r_2$$

$$r_4 \leftarrow r_4 - \frac{3}{2}r_2$$

echelon form of A^T

$$\begin{bmatrix} -2 & 2 & -3 \\ 0 & -2 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$A^T = \begin{bmatrix} -2 & 2 & -3 \\ 4 & -6 & 8 \\ -2 & -3 & 2 \\ -4 & 1 & -3 \end{bmatrix}$$

Basis for col A^T is $\left\{ \begin{bmatrix} -2 \\ 4 \\ -2 \\ -4 \end{bmatrix}, \begin{bmatrix} 2 \\ -6 \\ -3 \\ 1 \end{bmatrix} \right\}$

Basis for row $A = \left\{ \begin{bmatrix} 1 \\ 0 \\ 6 \\ 5 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 5/2 \\ 3/2 \end{bmatrix} \right\}$

$$\begin{bmatrix} -2 \\ 4 \\ -2 \\ -4 \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ 0 \\ 6 \\ 5 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ 1 \\ 5/2 \\ 3/2 \end{bmatrix} = -2 \begin{bmatrix} 1 \\ 0 \\ 6 \\ 5 \end{bmatrix} + 4 \begin{bmatrix} 0 \\ 1 \\ 5/2 \\ 3/2 \end{bmatrix}$$

$$= \begin{bmatrix} -2 \\ 4 \\ -2 \cdot 6 + 4 \cdot \frac{5}{2} \\ -2 \cdot 6 + 4 \cdot \frac{3}{2} \end{bmatrix} = \begin{bmatrix} -2 \\ 4 \\ -12 + 10 \\ -10 + 6 \end{bmatrix} = \begin{bmatrix} -2 \\ 4 \\ -2 \\ -4 \end{bmatrix}$$

$$\begin{bmatrix} 2 \\ -6 \\ -3 \\ 1 \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ 0 \\ 6 \\ 5 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ 1 \\ 5/2 \\ 3/2 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 0 \\ 6 \\ 5 \end{bmatrix} + (-6) \begin{bmatrix} 0 \\ 1 \\ 5/2 \\ 3/2 \end{bmatrix}$$

Idea of writing one basis in term of another.

Let $V \subseteq \mathbb{R}^m$ be a subspace, and

note $m \geq n$ so that B and C are linearly indep.

$B = \{b_1, b_2, \dots, b_n\}$ be a basis of V and

$C = \{c_1, c_2, \dots, c_n\}$ be another basis of V .

Define $B = [b_1 : b_2 : \dots : b_n] \in \mathbb{R}^{m \times n}$ and $C = [c_1 : c_2 : \dots : c_n] \in \mathbb{R}^{m \times n}$

Since B spans V then $x \in V$ implies there is some $u \in \mathbb{R}^n$ such that $x = Bu$.

Since C spans V there is $v \in \mathbb{R}^n$ so $x = Cv$.

By the unique representation theorem given a fixed x there is only one u such that $x = Bu$

only one v such that $x = Cv$.

Therefore u depends on x like a function of x .

Notation $u = \begin{bmatrix} x \end{bmatrix}_B = f(x) \in \mathbb{R}^n$

means some function of x

Similarly $v = [x]_e = g(x) \in \mathbb{R}^n$
some function of x .

Goal is to find a relationship between u and v .

Since $b_i \in V$ then we can solve $b_i = Cv$ for some $v \in \mathbb{R}^n$
notation $v = [b_i]_e$

$c_i \in V$ then we can solve $c_i = Bu$ for some $u \in \mathbb{R}^n$
notation $u = [c_i]_B$

Thus

$$b_i = C [b_i]_e \quad \text{and} \quad c_i = B [c_i]_B \quad \text{for every } i$$

Now

$$B = [b_1 \mid b_2 \mid \dots \mid b_n] = [C [b_1]_e \mid C [b_2]_e \mid \dots \mid C [b_n]_e]$$
$$= C \left[[b_1]_e \mid [b_2]_e \mid \dots \mid [b_n]_e \right]$$

Now

$$x = B [x]_B = C \left[[b_1]_e \mid [b_2]_e \mid \dots \mid [b_n]_e \right] [x]_B$$

also

$$x = C [x]_e$$

Thus

$$C \left[[b_1]_e \mid [b_2]_e \mid \dots \mid [b_n]_e \right] [x]_B = C [x]_e$$

$$C \left\{ \left[[b_1]_e \mid [b_2]_e \mid \dots \mid [b_n]_e \right] [x]_B - [x]_e \right\} = 0.$$

Now \mathcal{C} is a basis, so the columns of C are linearly independent. This means $\text{Nul } C = \{0\}$.

$$\begin{bmatrix} [b_1]_{\mathcal{C}} & \vdots & [b_2]_{\mathcal{C}} & \cdots & [b_n]_{\mathcal{C}} \end{bmatrix} [x]_{\mathcal{B}} \sim [x]_{\mathcal{C}} \in \text{Nul } C$$

so

$$\begin{bmatrix} [b_1]_{\mathcal{C}} & \vdots & [b_2]_{\mathcal{C}} & \cdots & [b_n]_{\mathcal{C}} \end{bmatrix} [x]_{\mathcal{B}} = [x]_{\mathcal{C}}$$

Change of basis matrix
from the \mathcal{B} basis to the \mathcal{C} basis

Notation

$$P_{\mathcal{C} \leftarrow \mathcal{B}} = \begin{bmatrix} [b_1]_{\mathcal{C}} & \vdots & [b_2]_{\mathcal{C}} & \cdots & [b_n]_{\mathcal{C}} \end{bmatrix} \in \mathbb{R}^{n \times n}$$

If I had written the book I'd have denoted this matrix as $[C \leftarrow B]$

By symmetry

$$\begin{bmatrix} [c_1]_{\mathcal{B}} & \vdots & [c_2]_{\mathcal{B}} & \cdots & [c_n]_{\mathcal{B}} \end{bmatrix} [x]_{\mathcal{C}} = [x]_{\mathcal{B}}$$

Notation

$$P_{\mathcal{B} \leftarrow \mathcal{C}} = \begin{bmatrix} [c_1]_{\mathcal{B}} & \vdots & [c_2]_{\mathcal{B}} & \cdots & [c_n]_{\mathcal{B}} \end{bmatrix} \in \mathbb{R}^{n \times n}$$

Note that

$$P_{\mathcal{B} \leftarrow \mathcal{C}} P_{\mathcal{C} \leftarrow \mathcal{B}} = I \quad \text{and} \quad P_{\mathcal{C} \leftarrow \mathcal{B}} P_{\mathcal{B} \leftarrow \mathcal{C}} = I$$

invertible matrices

What is $[b_i]_{\mathcal{B}} = ?$ and $[c_i]_{\mathcal{C}} = ?$

Answer $[b_i]_{\mathcal{B}} = e_i$ and $[c_i]_{\mathcal{C}} = e_i$

why $\mathcal{B}[b_i]_{\mathcal{B}} = b_i$

and. $\mathcal{B} e_i = b_i$