

Gram-Schmidt

$\|v_i\|$

$p=3$

$$v_1 = u_1$$

$$q_1 = \frac{v_1}{\|v_1\|}$$

$$v_2 = u_2 - (q_1 \cdot u_2) q_1$$

$$q_2 = \frac{v_2}{\|v_2\|}$$

$$v_3 = u_3 - (q_1 \cdot u_3) q_1 - (q_2 \cdot u_3) q_2$$

$$q_3 = \frac{v_3}{\|v_3\|}$$

$$\begin{bmatrix} u_1 & u_2 & u_3 \\ \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots \end{bmatrix}_{n \times 3} = \begin{bmatrix} q_1 & q_2 & q_3 \\ \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots \end{bmatrix}_{n \times 3} \begin{bmatrix} \|v_1\| & q_1 \cdot u_2 & q_1 \cdot u_3 \\ 0 & \|v_2\| & q_2 \cdot u_3 \\ 0 & 0 & \|v_3\| \end{bmatrix}_{3 \times 3}$$

$n=3$

Suppose $\left\{ \overset{u_1}{\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}}, \overset{u_2}{\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}}, \overset{u_3}{\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}} \right\}$ linearly independent and so a basis

$$\|v_1\| = \left\| \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right\| = \sqrt{2}$$

$$v_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$q_1 = \frac{v_1}{\|v_1\|} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \\ 0 \end{bmatrix}$$

$$v_2 = u_2 - (q_1 \cdot u_2) q_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} - \left(\frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right) \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} - \left(\frac{1}{\sqrt{2}} \right) \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} - \begin{bmatrix} 1/2 \\ 1/2 \\ 0 \end{bmatrix} = \begin{bmatrix} 1/2 \\ -1/2 \\ 1 \end{bmatrix}$$

$$\|v_2\| = \sqrt{\frac{1}{4} + \frac{1}{4} + 1} = \sqrt{3/2}$$

$$q_2 = \frac{v_2}{\|v_2\|} = \frac{1}{\sqrt{3/2}} \begin{bmatrix} 1/2 \\ -1/2 \\ 1 \end{bmatrix} = \begin{bmatrix} 1/\sqrt{6} \\ -1/\sqrt{6} \\ 2/\sqrt{6} \end{bmatrix} = \begin{bmatrix} 1/\sqrt{6} \\ -1/\sqrt{6} \\ \sqrt{2/3} \end{bmatrix}$$

$$v_3 = u_3 - (q_1 \cdot u_3) q_1 - (q_2 \cdot u_3) q_2$$

...

$$\begin{aligned}
&= \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} - \left(\frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right) \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - \left(\frac{1}{\sqrt{3/2}} \begin{bmatrix} 1/2 \\ 1/2 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right) \frac{1}{\sqrt{3/2}} \begin{bmatrix} 1/2 \\ 1/2 \\ 1 \end{bmatrix} \\
&= \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} - \left(\frac{1}{\sqrt{2}} \right) \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - \left(\frac{1}{\sqrt{3/2}} \frac{1}{2} \right) \frac{1}{\sqrt{3/2}} \begin{bmatrix} 1/2 \\ 1/2 \\ 1 \end{bmatrix} \\
&= \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - \frac{2}{3} \frac{1}{2} \begin{bmatrix} 1/2 \\ 1/2 \\ 1 \end{bmatrix} = \begin{bmatrix} -1/2 \\ 1/2 \\ 1 \end{bmatrix} - \begin{bmatrix} 1/6 \\ -1/6 \\ 1/3 \end{bmatrix} = \begin{bmatrix} -2/3 \\ 2/3 \\ 2/3 \end{bmatrix} \\
&\|v_3\| = \sqrt{\frac{4}{9} + \frac{4}{9} + \frac{4}{9}} = \sqrt{\frac{4}{3}} = \frac{2}{\sqrt{3}}
\end{aligned}$$

$$q_3 = \frac{v_3}{\|v_3\|} = \frac{\sqrt{3}}{2} \begin{bmatrix} -2/3 \\ 2/3 \\ 2/3 \end{bmatrix} = \begin{bmatrix} -1/\sqrt{3} \\ 1/\sqrt{3} \\ 1/\sqrt{3} \end{bmatrix}$$

$$Q = \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{6} & -1/\sqrt{3} \\ 1/\sqrt{2} & -1/\sqrt{6} & 1/\sqrt{3} \\ 0 & \sqrt{2/3} & 1/\sqrt{3} \end{bmatrix} \quad R = \begin{bmatrix} \sqrt{2} & 1/\sqrt{2} & 1/\sqrt{2} \\ 0 & \sqrt{3/2} & 1/\sqrt{6} \\ 0 & 0 & 2/\sqrt{3} \end{bmatrix}$$

Check this

$$\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{6} & -1/\sqrt{3} \\ 1/\sqrt{2} & -1/\sqrt{6} & 1/\sqrt{3} \\ 0 & \sqrt{2/3} & 1/\sqrt{3} \end{bmatrix} \begin{bmatrix} \sqrt{2} & 1/\sqrt{2} & 1/\sqrt{2} \\ 0 & \sqrt{3/2} & 1/\sqrt{6} \\ 0 & 0 & 2/\sqrt{3} \end{bmatrix}$$

This can be seen as a way of factoring a matrix $A \in \mathbb{R}^{m \times n}$ with linearly independent columns as

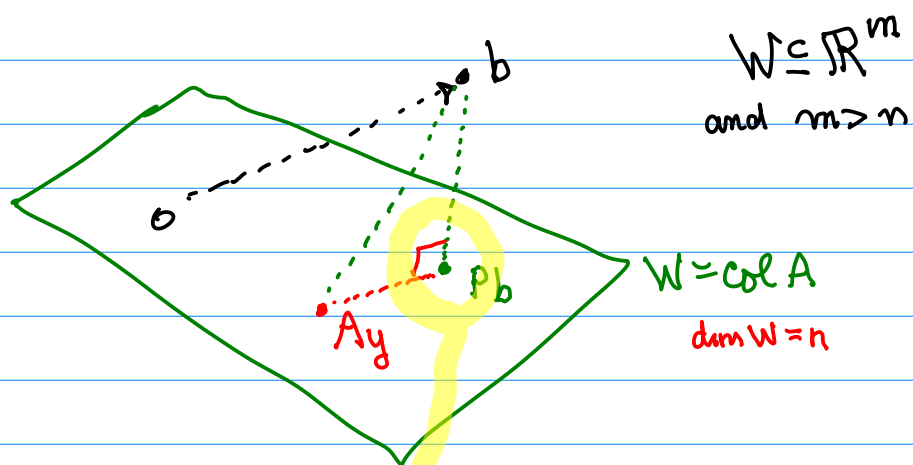
$$A = Q R \leftarrow \text{upper triangular (algebraic)}$$

$m \times n \quad m \times n \quad n \times n$


 has orthonormal columns $Q^T Q = I$
 (geometric)

$A \in \mathbb{R}^{m \times n}$ with linearly independent columns.

Note if $b \notin \text{col } A$ then $Ax = b$ has no solutions



Idea since we can't solve $Ax = b$ instead let's minimize $\|Ax - b\|$.

$$P = A(A^T A)^{-1} A^T$$

$$(Pb - Ay) \cdot (b - Pb)$$

Since P is a projection onto W then $Pb \in W$

Since $W = \text{col } A$ then $Ay \in W$

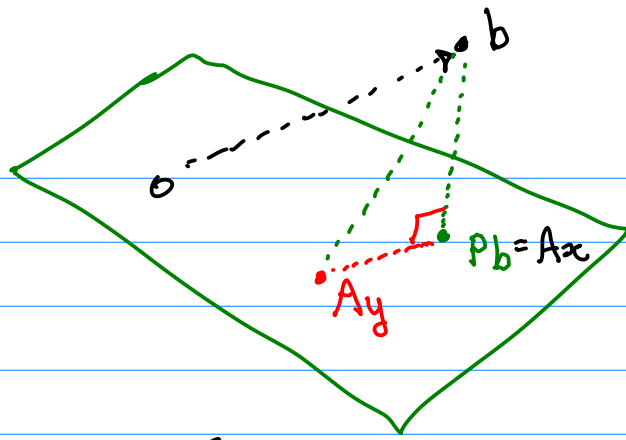
Consequently since W is a subspace $Pb - Ay \in W$

Since $b - Pb$ is orthogonal to any vector in W
then $w \cdot (b - Pb) = 0$ for every $w \in W$

$$\text{so, } (Pb - Ay) \cdot (b - Pb) = 0$$

so that's really a right angle.

Pythagorean theorem:



$$\|A_y - p_b\|^2 + \|b - p_b\|^2 = \|b - A_y\|^2$$

Therefore $\|b - p_b\| \leq \|b - A_y\|$ for every $y \in \mathbb{R}^n$.

Idea since we can't solve $Ax = b$ instead let's minimize $\|Ax - b\|$.

To find the minimizer all I need is to solve $Ax = p_b$

$$P = A(A^T A)^{-1} A^T$$

$$A \in \mathbb{R}^{m \times n}$$

Thus

$$Ax = A(A^T A)^{-1} A^T b$$

$$A^T \in \mathbb{R}^{n \times m}$$

$$A^T Ax = A^T A(A^T A)^{-1} A^T b$$

Thus

$$\underbrace{A^T A}_{n \times m \times m \times n} x = \underbrace{A^T b}_{n \times m}$$

← normal equations
 $x \in \mathbb{R}^n$
 $b \in \mathbb{R}^m$

$$A^T A \in \mathbb{R}^{n \times n}$$

and $A^T A$ is invertible because the columns of A are linearly independent.

In summary solving $A^T Ax = A^T b$ is the same as minimizing $\|Ax - b\|$.

Could solve $A^T A x = A^T b$ using the augmented matrix

$$\left[\begin{array}{c|c} A^T A & A^T b \end{array} \right]$$

and Gaussian elimination.

Better to use Gram-Schmidt...

$$A = Q R \quad \begin{matrix} m \times n & m \times n & n \times n \end{matrix} \quad \leftarrow \text{upper triangular (algebraic)}$$

$\uparrow$ has orthonormal columns $Q^T Q = I$
(geometric)

Plug the factorization in

$$A^T = R^T Q^T$$

note A is not invertible (in general)
 Q is not invertible (in general)
but R is square and invertible.

$$A^T A x = A^T b$$

$$R^T Q^T Q R x = R^T Q^T b$$

$$R^T R x = R^T Q^T b$$

$$R^T (R x - Q^T b) = 0$$

$$R x - Q^T b = 0$$

$\rightarrow$ since R^T is also invertible

Finally solving $R x = Q^T b$ finds the minimum of $\|A x - b\|$

$\uparrow$
easy to solve, since R is upper triangular
we can use backsubstitution to find x .

Suppose $b \in \text{col } A$. Then $Ax = b$ has a solution, that means minimum of $\|Ax - b\|$ is zero and the minimizer is the solution of $Ax = b$.

Use $A = QR$ to solve $Ax = b$ when $b \in \text{Col } A$ by solving $Rx = Q^T b$ for x .

Note rephrasing how to find an exact solution as a minimization problem can be useful in numerical contexts where due to rounding errors there is no solution that exactly satisfies the problem.