

Math/CS 467/667 Take Home Midterm Answer Key

1. Let B be the matrix given by

```
1.8635  1.7135  1.9593  1.5685  1.6521
1.7135  1.8984  1.7439  1.6447  1.5253
1.9593  1.7439  2.6919  2.2635  1.6423
1.5685  1.6447  2.2635  2.2056  1.2430
1.6521  1.5253  1.6423  1.2430  1.5505
```

(i) Use the power method to find the largest eigenvalue.

The following Matlab script

```
1 clear all;
2 getB;
3 v=ones(5,1);
4 disp(sprintf("%10s %15s","iteration","lambda"));
5 for i=1:8
6     w=B*v;
7     lambda=(v'*w)/(v'*v);
8     disp(sprintf("%10d %15.10f",i,lambda));
9     [y,i]=max(abs(w));
10    alpha=w(i);
11    v=w/alpha;
12 end
```

along with the file `getB.m` given by

```
1 B=[
2   1.8635  1.7135  1.9593  1.5685  1.6521;
3   1.7135  1.8984  1.7439  1.6447  1.5253;
4   1.9593  1.7439  2.6919  2.2635  1.6423;
5   1.5685  1.6447  2.2635  2.2056  1.2430;
6   1.6521  1.5253  1.6423  1.2430  1.5505];
```

implements the power method and produces the output

```
iteration      lambda
      1  8.8244200000
      2  8.9143037789
      3  8.9148122076
      4  8.9148171504
      5  8.9148171993
      6  8.9148171997
      7  8.9148171998
      8  8.9148171998
```

From the output we see that the largest eigenvalue of B is about 8.9148.

(ii) Use the inverse power method to find the smallest eigenvalue.

A slight modification of the above code to implement the inverse power method gives

```
1 clear all
```

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```
2 getB;
3 v=ones(5,1);
4 disp(sprintf("%10s %15s","iteration","lambda"));
5 for i=1:8
6     w=B\v;
7     lambda=(v'*v)/(v'*w);
8     disp(sprintf("%10d %15.10f",i,lambda));
9     [y,i]=max(abs(w));
10    alpha=w(i);
11    v=w/alpha;
12 end
```

with output

iteration	lambda
1	2.4124813641
2	0.0118139793
3	0.0116738143
4	0.0116543513
5	0.0116513976
6	0.0116509497
7	0.0116508818
8	0.0116508715

From the output we see that the smallest eigenvalue of B is about 0.011651.

(iii) [*] Use the shifted inverse power method to find one more eigenvalue.

We decide to shift by $s = 2$ to find another eigenvalue. A modification of the above code to implement the shifted inverse power method gives

```
1 clear all
2 getB;
3 v=ones(5,1);
4 disp(sprintf("%10s %15s","iteration","lambda"));
5 s=2;
6 BS=B-s*eye(5);
7 for i=1:15
8     w=BS\v;
9     lambda=(v'*v)/(v'*w)+s;
10    disp(sprintf("%10d %15.10f",i,lambda));
11    [y,i]=max(abs(w));
12    alpha=w(i);
13    v=w/alpha;
14 end
```

with output

iteration	lambda
1	9.4040886684

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```
2 -10.2345718845
3 0.7178667250
4 0.8711806295
5 0.8831941425
6 0.8864238859
7 0.8876008577
8 0.8880553351
9 0.8882374136
10 0.8883127823
11 0.8883448616
12 0.8883588253
13 0.8883650093
14 0.8883677831
15 0.8883690388
```

From the output we see that another eigenvalue of B is about 0.88837.

For reference note that the complete set of eigenvalue of B may be found using the built-in Matlab command `eig` and are given by

```
>> eig(B)
ans =

0.0116508697060692
0.0299229096932658
0.3651389250153996
0.8883700958342445
8.9148171997510222
```

2. Consider the two-point linear boundary problem

$$\begin{cases} y'' + \cos(x)y' - (x^2 + 1)y = 2 \\ y(-2) = y(2) = -1. \end{cases}$$

(i) Solve the above boundary problem for grid sizes of $h = 4/n$ where $n = 4, 8, 16, 32, \dots, 256$. Plot your solutions.

The Matlab code for this consisted of the script

```

1 clear all
2 p=@(x) -cos(x);
3 q=@(x) x.*x+1;
4 r=@(x) 2+0*x;
5
6 dataout=fopen("data2.dat","w");
7 for N=2.^[2:8]
8     fprintf(dataout,"# n=%d\n",N);
9     [xn,yn]=solvebvp(p,q,r,-2,2,N,-1,-1);
10    for j=1:length(xn)
11        fprintf(dataout,"%22.15e %22.15e\n",xn(j),yn(j));
12    end
13    fprintf(dataout,"\n\n");
14 end
15 fclose(dataout);

```

along with `solvebvp.m` for solving for the two-point boundary value problem

```

1 %solvebvp.m -- Solve boundary value problem
2 % y''=py'+qy+r
3 % y(a)=g1, y(b)=g2
4 function [xn,yn]=solvebvp(p,q,r,a,b,N,g1,g2)
5     h=(b-a)/N;
6     xn=[a:h:b]';
7     Aa=-(1+h/2*p(xn(3:N)));
8     Ab=2+h^2*q(xn(2:N));
9     Ac=(-1+h/2*p(xn(2:N-1)));
10    f=-h^2*r(xn(2:N));
11    f(1)=f(1)+(1+h/2*p(xn(2)))*g1;
12    f(N-1)=f(N-1)+(1-h/2*p(xn(N)))*g2;
13    ym=tridiag(Aa,Ab,Ac,f);
14    yn=[g1; ym; g2];

```

and the tridiagonal solver `tridiag.m` developed in class

```

1 function f=tridiag(a,b,c,f)
2     n=length(b);
3     for i=1:n-1

```

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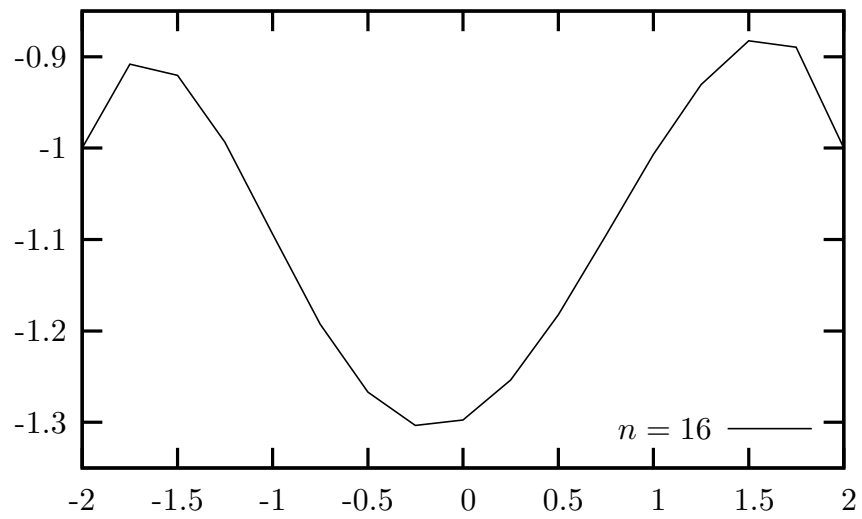
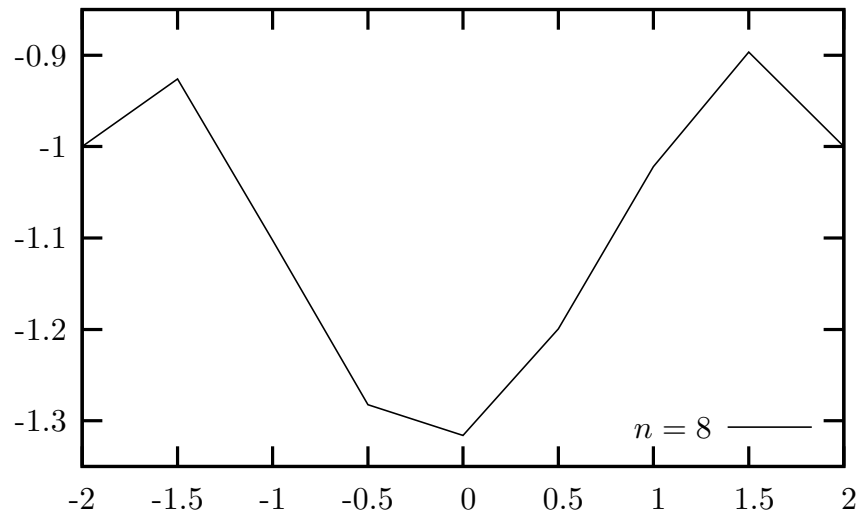
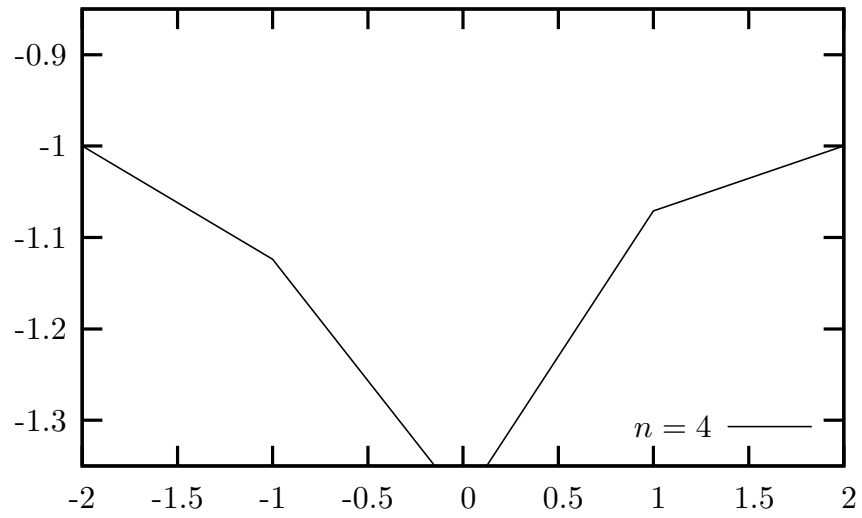
```
4      a(i)=a(i)/b(i);
5      b(i+1)=b(i+1)-a(i)*c(i);
6  end
7  for i=1:n-1
8      f(i+1)=f(i+1)-a(i)*f(i);
9  end
10     f(n)=f(n)/b(n);
11     for i=n-1:-1:1
12         f(i)=(1/b(i))*(f(i)-c(i)*f(i+1));
13     end
14 end
```

This code creates a data file `data2.dat` consisting of the solution for each resolution separated by two blank lines. We plot the data file using the plotting program `gnuplot` along with the script `data2.gnu` which contains the commands

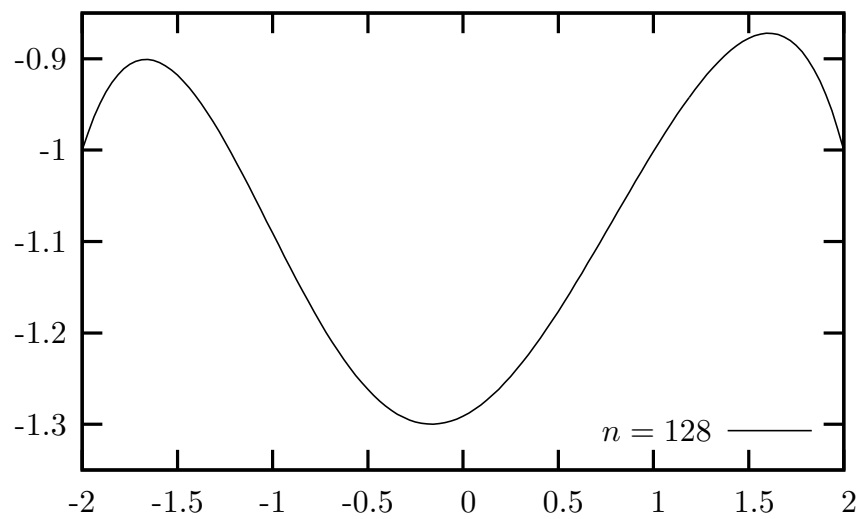
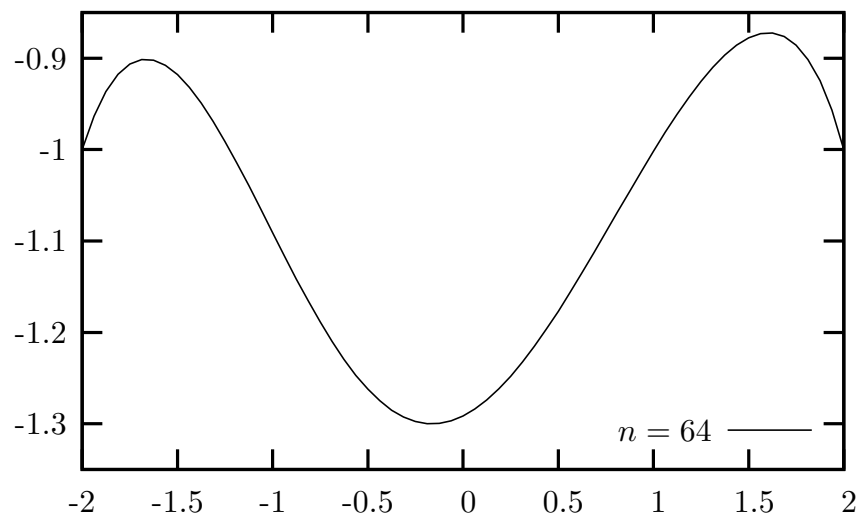
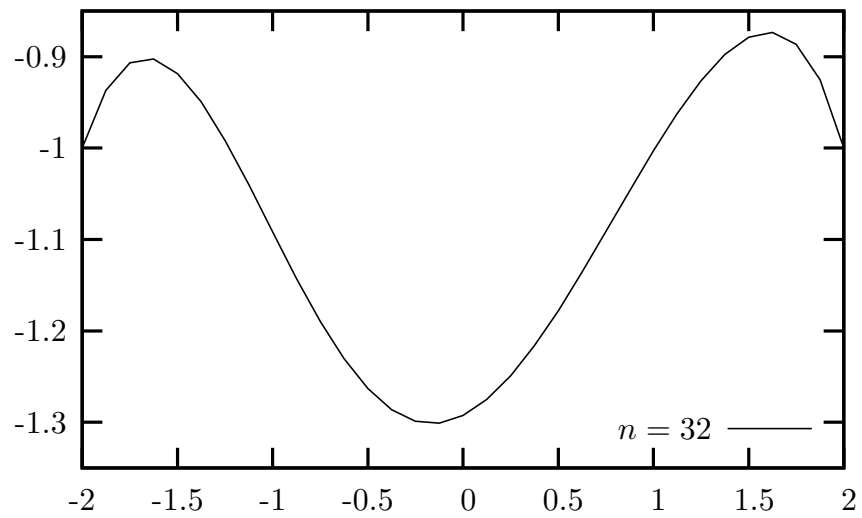
```
1 set terminal pstex
2 set style data lines
3 set size 0.8,0.8
4 set key spacing 1.2
5 set key bottom
6 set output "data2-0.tex"
7 plot [:] [-1.35:-0.85] "data2.dat" index 0 ti "$n=4$"
8 set output "data2-1.tex"
9 plot [:] [-1.35:-0.85] "data2.dat" index 1 ti "$n=8$"
10 set output "data2-2.tex"
11 plot [:] [-1.35:-0.85] "data2.dat" index 2 ti "$n=16$"
12 set output "data2-3.tex"
13 plot [:] [-1.35:-0.85] "data2.dat" index 3 ti "$n=32$"
14 set output "data2-4.tex"
15 plot [:] [-1.35:-0.85] "data2.dat" index 4 ti "$n=64$"
16 set output "data2-5.tex"
17 plot [:] [-1.35:-0.85] "data2.dat" index 5 ti "$n=128$"
18 set output "data2-6.tex"
19 plot [:] [-1.35:-0.85] "data2.dat" index 6 ti "$n=256$"
```

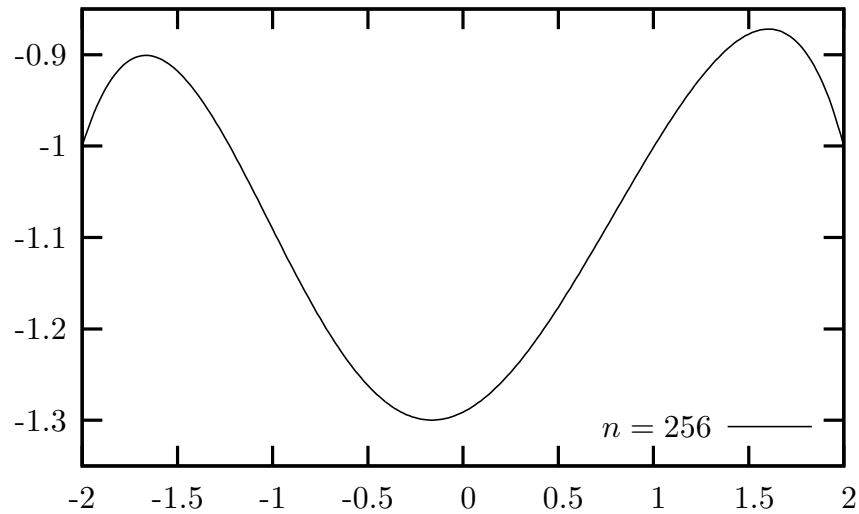
The resulting output was

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(ii) Calculate the value of $y(1)$ to 5 significant digits.

The following Matlab code uses the relationship that $y_j \approx y(1)$ for $j = 1 + 3n/4$. Note that 0.05 is added in the code and the integer part is taken to ensure correct rounding.

```

1 clear all
2 p=@(x) -cos(x);
3 q=@(x) x.*x+1;
4 r=@(x) 2+0*x;
5
6 disp(sprintf("%5s %5s %8s %15s","n","j","xj","yj"));
7 for N=2.^[5:12]
8     [xn,yn]=solvebvp(p,q,r,-2,2,N,-1,-1);
9     j=floor(3/4*N+1.05);
10    disp(sprintf("%5d %5d %8.4g %15.10g",N,j,xn(j),yn(j)));
11 end

```

The output is

n	j	xj	yj
32	25	1	-1.002991565
64	49	1	-1.001970132
128	97	1	-1.001713523
256	193	1	-1.001649292
512	385	1	-1.001633229
1024	769	1	-1.001629213
2048	1537	1	-1.001628209
4096	3073	1	-1.001627958

It is clear that $y(1) \approx -1.0016$ to 5 significant digits.

(iii) [*] Numerically verify the order of convergence of your solution with theoretical expectations.

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Since this ordinary differential equation two-point boundary value problem solver employs a 2nd order method, theoretical expectations are that the error decreases by a factor of 4 every time n is doubled. The following Matlab program computes an approximation for the exact answer using $n = 2^{15}$ and then checks from $n = 16, 32, \dots, 1024$ that the error decreases by a factor of 4 each time.

```
1 clear all
2 p=@(x) -cos(x);
3 q=@(x) x.*x+1;
4 r=@(x) 2+0*x;
5
6 N1=[2.^[4:10],2^15];
7 M=length(N1);
8 for i=1:M
9     [xn,yn]=solvebvp(p,q,r,-2,2,N1(i),-1,-1);
10    j=floor(3/4*N1(i)+1.05);
11    y1(i)=yn(j);
12 end
13 e1=y1-y1(M);
14
15 disp(sprintf("%5s %16s %20s %16s","n","y","error","ratio"));
16 for i=2:M-1
17     disp(sprintf("%5d %16.11f %20.12e %16.12f",...
18         N1(i),y1(i),e1(i),e1(i-1)/e1(i)));
19 end;
```

The output is

n	y	error	ratio
32	-1.00299156465	-1.363686014051e-03	3.940237053496
64	-1.00197013225	-3.422536077700e-04	3.984431378054
128	-1.00171352333	-8.564469614281e-05	3.996203188103
256	-1.00164929190	-2.141326550475e-05	3.999609313385
512	-1.00163322908	-5.350441215413e-06	4.002149475649
1024	-1.00162921306	-1.334424415633e-06	4.009549849906

The fact that the list of ratios given in the last column of the above table is close to 4 verifies the method is converging with second order.

3. Consider the initial value problem

$$\begin{cases} y' = \cos(y) + \cos(x) \\ y(0) = 0. \end{cases}$$

(i) Construct a 3rd-order Taylor method for solving this problem.

In general, a third order Taylor method has the update rule

$$y_{n+1} = y_n + hf_0(x_n, y_n) + \frac{h^2}{2}f_1(x_n, y_n) + \frac{h^3}{3!}f_2(x_n, y_n)$$

where

$$f_i(x, y) = \frac{d^i}{dx^i} f(x, y).$$

The following Maple script creates C and Matlab code for a Taylor method with order N and forcing function f .

```

1 #Build a Taylor method for y'=f of order N
2 restart;
3 with(codegen):
4 N:=3;
5 f:=cos(y(x))+cos(x);
6 s:=[seq(diff(y(x),x$(N-i+1))=F||(N-i),i=1..N),y(x)=yn,x=xn];
7 r[1]:=f;
8 for i from 2 to N
9 do
10     r[i]:=diff(r[i-1],x);
11 end;
12 jet:=seq(F||(i-1)=subs(s,r[i]),i=1..N);
13 t:=yn;
14 for i from 1 to N
15 do
16     t:=t+h^i/i!*F||(i-1);
17 end;
18 t2:=horner(t,h);
19 jeto:=optimize([jet,yn=t2]);
20 C([jeto]);

```

The output of this script is

```

t1 = cos(yn);
t3 = cos(xn);
F0 = t1+t3;
t4 = sin(yn);
t6 = sin(xn);
F1 = -t4*F0-t6;
t7 = F0*F0;
F2 = -t1*t7-t4*F1-t3;

```

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$$y_n = y_n + (F_0 + (F_1/2.0 + F_2*h/6.0)*h)*h;$$

which we embed into Matlab to make the Taylor integrator

```
1 function yn=taylor3a(x0,y0,xn,N)
2   h=(xn-x0)/N;
3   xn=x0;
4   yn=y0;
5   for n=1:N
6
7   % The following Taylor time step was generated by Maple
8       t1 = cos(yn);
9       t3 = cos(xn);
10      F0 = t1+t3;
11      t4 = sin(yn);
12      t6 = sin(xn);
13      F1 = -t4*F0-t6;
14      t7 = F0*F0;
15      F2 = -t1*t7-t4*F1-t3;
16      yn = yn+(F0+(F1/2.0+F2*h/6.0)*h)*h;
17
18      xn=x0+h*n;
19  end;
```

(ii) Compute $y(10)$ to 5 significant digits using your 3rd-order Taylor method.

The script for computing $y(10)$ is given by

```
1 clear all
2 disp(sprintf("%5s %16s", "n", "y"));
3 for N=2.^[3:8];
4   y=taylor3a(0,0,10,N);
5   disp(sprintf("%5d %16.11f", N, y));
6 end
```

with output

n	y
8	0.86457548562
16	0.86482318490
32	0.86411078690
64	0.86398264165
128	0.86396474966
256	0.86396241613

It is clear that $y(10) \approx 0.86396$ to 5 significant digits.

(iii) [*] Numerically verify the order of convergence of your code to be 3rd order.

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Since this is a 3rd order method, theoretical expectations are that the error decreases by a factor of $2^3 = 8$ every time n is doubled. The following Matlab program computes an approximation for the exact answer using $n = 2^{15}$ and then checks from $n = 16, 32, \dots, 1024$ that the error decreases by a factor of 8 each time.

```
1 N1=[2.^[3:10],2^15];
2 M=length(N1);
3 for i=1:M
4   y1(i)=taylor3a(0,0,10,N1(i));
5 end
6 e1=y1-y1(M);
7
8 disp(sprintf("%5s %16s %20s %16s","n","y","error","ratio"));
9 for i=2:M-1
10    disp(sprintf("%5d %16.11f %20.12e %16.12f",...
11                N1(i),y1(i),e1(i),e1(i-1)/e1(i)));
12 end;
```

The output is

n	y	error	ratio
16	0.86482318490	8.611087197790e-04	0.712348420285
32	0.86411078690	1.487107152024e-04	5.790495450224
64	0.86398264165	2.056547146689e-05	7.231087088949
128	0.86396474966	2.673474348347e-06	7.692413985423
256	0.86396241613	3.399449226560e-07	7.864433824924
512	0.86396211901	4.283216037404e-08	7.936674678264
1024	0.86396208156	5.374421463422e-09	7.969631832105

The fact that the list of ratios given in the last column of the above table is close to 8 verifies the method is converging with third order.

4. Consider the general initial value problem

$$\begin{cases} y' = f(x, y) \\ y(x_0) = y_0. \end{cases}$$

- (i) Starting with Euler's explicit method, use Richardson extrapolation with step sizes $2h$ and $3h$ to create a method that is 2nd-order convergent.

Since Euler's explicit method is first order, it has an asymptotic error formula of the form

$$y(x) - y_h(x) = hD(x) + h^2E(x) + \mathcal{O}(h^3)$$

where $y(x)$ is the exact solution and y_h is the approximation obtained by Euler's method. It may be assumed that $D(x)$ and $E(x)$ do not depend greatly on h . Therefore

$$y(x) - y_{2h}(x) = 2hD(x) + 4h^2E(x) + \mathcal{O}(h^3)$$

and

$$y(x) - y_{3h}(x) = 3hD(x) + 9h^2E(x) + \mathcal{O}(h^3).$$

Multiplying the first equation by 3, the second by 2 and subtracting eliminates $D(x)$ and obtains

$$y(x) - 3y_{2h}(x) + 2y_{3h}(x) = -6h^2E(x) + \mathcal{O}(h^3).$$

Therefore, the method given by $y(x) \approx 3y_{2h}(x) - 2y_{3h}(x)$ is second order.

- (ii) Starting with Euler's explicit method, use Richardson extrapolation with step sizes h , $2h$ and $3h$ to create a method that is 3rd-order convergent.

Starting with

$$y(x) - y_h(x) = hD(x) + h^2E(x) + \mathcal{O}(h^3)$$

and

$$y(x) - y_{2h}(x) = 2hD(x) + 4h^2E(x) + \mathcal{O}(h^3).$$

multiply the first equation by 2 and subtract to obtain

$$y(x) - 2y_h(x) + y_{2h}(x) = -2h^2E(x) + \mathcal{O}(h^3).$$

Now, multiply this result by 3 and subtract from the answer to the previous part to obtain

$$-2y(x) + 6y_h(x) - 6y_{2h}(x) + 2y_{3h}(x) = \mathcal{O}(h^3).$$

Therefore, the method given by $y(x) \approx 3y_h(x) - 3y_{2h}(x) + y_{3h}(x)$ is third order.

- (iii) [*] Use the 3rd-order method created above to compute $y(2)$ to 5 significant digits when $f(x, y) = -xy + (4x/y)$, $x_0 = 0$ and $y_0 = 1$.

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The extrapolation method may be coded as

```
1 function yn=richard4c(x0,y0,xn,f,N)
2   h=(xn-x0)/N;
3   xn=x0;
4   yn=y0;
5   for n=1:N
6     y1=euler4c(xn,yn,xn+h,f,6);
7     y2=euler4c(xn,yn,xn+h,f,3);
8     y3=euler4c(xn,yn,xn+h,f,2);
9     yn=3*(y1-y2)+y3;
10    xn=x0+h*n;
11  end;
```

where the Euler method is given by

```
1 function yn=euler4c(x0,y0,xn,f,N)
2   h=(xn-x0)/N;
3   xn=x0;
4   yn=y0;
5   for n=1:N
6     yn=yn+h*f(xn,yn);
7     xn=x0+h*n;
8   end;
```

Test this method using the script

```
1 clear all
2 f=@(x,y) -x*y+(4*x/y);
3 N1=[2.^[3:10],2^15];
4 M=length(N1);
5 for i=1:M
6   y1(i)=richard4c(0,1,2,f,N1(i));
7 end
8 e1=y1-y1(M);
9
10 disp(sprintf("%5s %16s %20s %16s","n","y","error","ratio"));
11 for i=2:M-1
12   disp(sprintf("%5d %16.11f %20.12e %16.12f",...
13     N1(i),y1(i),e1(i),e1(i-1)/e1(i)));
14 end;
```

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which produces the output

n	y	error	ratio
16	1.98622917476	1.340517712323e-05	7.069641462451
32	1.98621746967	1.700086410983e-06	7.884997513436
64	1.98621598185	2.122726134868e-07	8.008976678891
128	1.98621579605	2.647186536642e-08	8.018800736123
256	1.98621577289	3.303734619209e-09	8.012709378200
512	1.98621576999	4.126134989235e-10	8.006850546160
1024	1.98621576963	5.156652882476e-11	8.001575989838

Therefore $y(2) \approx 1.98622$ to 5 significant digits. Moreover, the fact that the list of ratios given in the last column of the above table is close to 8 verifies the method is converging with third order.