

moved from the last slot to the  $j$ th slot. The determinant of this matrix is therefore  $(-1)^{k-j} \det M^{kj}$  — one factor of  $-1$  because of the minus signs on the column of  $B_{ik}$ 's, and  $k - j - 1$  more factors of  $-1$  from interchanging that column with the succeeding  $k - j - 1$  columns to move it back to its rightful place on the right end. In short, the application of Cramer's rule to the system (B.5) yields

$$\frac{\partial g_j}{\partial y_k}(\mathbf{a}, b_k) = (-1)^{k-j} \frac{\det M^{kj}}{\det M^{kk}}.$$

Now we are done. Substitute this result back into (B.4), noting that  $(-1)^{-j} = (-1)^j$ , and recall (B.3):

$$\begin{aligned} \frac{\partial G}{\partial y_k}(\mathbf{a}, b_k) &= \sum_{j=1}^{k-1} (-1)^{j+k} B_{kj} \frac{\det M^{kj}}{\det M^{kk}} + B_{kk} \\ &= \frac{\sum_{j=1}^k (-1)^{j+k} B_{kj} \det M^{kj}}{\det M^{kk}} = \frac{\det B}{\det M^{kk}}. \end{aligned}$$

*self correcting typo...*

### 3.9 Theorem (The Implicit Function Theorem for a System of Equations).

Let  $\mathbf{F}(\mathbf{x}, \mathbf{y})$  be an  $\mathbb{R}^k$ -valued function of class  $C^1$  on some neighborhood of a point  $(\mathbf{a}, \mathbf{b}) \in \mathbb{R}^{n+k}$  and let  $B_{ij} = (\partial F_i / \partial y_j)(\mathbf{a}, \mathbf{b})$ . Suppose that  $\mathbf{F}(\mathbf{a}, \mathbf{b}) = \mathbf{0}$  and  $\det B \neq 0$ . Then there exist positive numbers  $r_0, r_1$  such that the following conclusions are valid.

- a. For each  $\mathbf{x}$  in the ball  $|\mathbf{x} - \mathbf{a}| < r_0$  there is a unique  $\mathbf{y}$  such that  $|\mathbf{y} - \mathbf{b}| < r_1$  and  $\mathbf{F}(\mathbf{x}, \mathbf{y}) = \mathbf{0}$ . We denote this  $\mathbf{y}$  by  $\mathbf{f}(\mathbf{x})$ ; in particular,  $\mathbf{f}(\mathbf{a}) = \mathbf{b}$ .
- b. The function  $\mathbf{f}$  thus defined for  $|\mathbf{x} - \mathbf{a}| < r_0$  is of class  $C^1$ , and its partial derivatives  $\partial_{x_j} \mathbf{f}$  can be computed by differentiating the equations  $\mathbf{F}(\mathbf{x}, \mathbf{f}(\mathbf{x})) = \mathbf{0}$  with respect to  $x_j$  and solving the resulting linear system of equations for  $\partial_{x_i} f_1, \dots, \partial_{x_i} f_k$ .

Note  $(\mathbf{a}, \mathbf{b}) \in \mathbb{R}^{n+k}$  means  $\mathbf{a} \in \mathbb{R}^n$  and  $\mathbf{b} \in \mathbb{R}^k$

$U \subseteq \mathbb{R}^{n+k}$ ,  $\mathbf{F}: U \rightarrow \mathbb{R}^k$

$$B = [B_{ij}] = \left[ \frac{\partial F_i}{\partial y_j}(\mathbf{a}, \mathbf{b}) \right] = \begin{bmatrix} \frac{\partial F_1}{\partial y_1} & \cdots & \frac{\partial F_1}{\partial y_k} \\ \vdots & & \vdots \\ \frac{\partial F_k}{\partial y_1} & \cdots & \frac{\partial F_k}{\partial y_k} \end{bmatrix}$$

$$\mathbf{F}(\mathbf{x}, \mathbf{y}) = \mathbf{0}$$

$$\Sigma(\mathbf{a}, \mathbf{b}) = 0 \dots$$

use this to define  $\mathbf{y}$  as a function of  $\mathbf{x}$ ...

Proof: By induction on  $k$ .

$k=1$  is Theorem 3.1 (base case)

Assume the theorem is true for  $k-1$  and try to prove it for  $k$ .

$$B = \begin{bmatrix} \frac{\partial F_1}{\partial y_1} & \dots & \frac{\partial F_1}{\partial y_k} \\ \vdots & \ddots & \vdots \\ \frac{\partial F_k}{\partial y_1} & \dots & \frac{\partial F_k}{\partial y_k} \end{bmatrix}$$

and  $\det B = 0$

where are they evaluated?

Let  $(a, b)$  be a point such that

$$F(a, b) = 0.$$

$$\det B = \sum_{j=1}^k (-1)^{k+j} B_{kj} \det M^{kj}$$

where  $M^{kj}$  is the cofactor matrix of  $B$  given by crossing out the  $k$ th row and  $j$ th column..

since  $\det B$  is not zero at least one term in the sum is non-zero..

Suppose  $B_{kk} \det M^{kk} \neq 0$  (for convenience of notation).

$$M^{kk} = \begin{bmatrix} \frac{\partial F_1}{\partial y_1} & \dots & \frac{\partial F_1}{\partial y_{k-1}} & \frac{\partial F_1}{\partial y_k} \\ \vdots & \ddots & \vdots & \vdots \\ \frac{\partial F_k}{\partial y_1} & \dots & \frac{\partial F_k}{\partial y_{k-1}} & \frac{\partial F_k}{\partial y_k} \end{bmatrix}$$

where are they evaluated?  
let  $(a, b)$  be a point such that  
 $F(a, b) = 0.$

$$\det M^{kk} = 0$$

$$F_1(x, y_1, \dots, y_{k-1}, y_k) = F_2(x, y_1, \dots, y_{k-1}, y_k) =$$

$$\dots = F_{k-1}(x, y_1, \dots, y_{k-1}, y_k) = 0$$

by induction hypothesis:

$$\begin{bmatrix} F_1 \\ \vdots \\ F_{k-1} \end{bmatrix} : \mathbb{R}^{n+1+(k-1)} \rightarrow \mathbb{R}^{k-1}$$

there exist a function  $g: \mathbb{R}^{n+1} \rightarrow \mathbb{R}^{k-1}$  such that

$$F_1(x, g(x, y_k), y_k) = F_2(x, g(x, y_k), y_k)$$

$$= F_{k-1}(x, g(x, y_k), y_k) = 0$$

To solve for all the  $y$ 's in terms of  $x$ , we need to solve for  $y_k$  in terms of  $x$ . **Theorem 3.1 again applies.**

We want to use  $F_k(x, g(x, y_k), y_k) = 0$  to solve for  $y_k$ .

Hypothesis needed  $\exists$  on some neighborhood  $\partial_y F(a, b) \neq 0$

Need to show: (use the hypothesis  $\det B \neq 0$ )

$$\frac{\partial F_k(x, g(x, y_k), y_k)}{\partial y_k} \neq 0$$

By the Chain rule

$$\frac{\partial F_k(x, g(x, y_k), y_k)}{\partial y_k} = \sum_{j=1}^{k-1} \left[ \frac{\partial F_k}{\partial y_j}(x, g(x, y_k), y_k) \right] \frac{\partial g_j(x, y_k)}{\partial y_k} + \left[ \frac{\partial F_k}{\partial y_k}(x, g(x, y_k), y_k) \right]$$

means  $\left. \frac{\partial F_k(x, y)}{\partial y_i} \right|_{(x, y) = (x, g(x, y_k), y_k)}$

$$\left. \frac{\partial F_k(x, g(x, y_k), y_k)}{\partial y_k} \right|_{(x, y_k) = (a, b_k)} = \sum_{j=1}^{k-1} B_{kj} \frac{\partial g_j(a, b_k)}{\partial y_k} + B_{kk}$$

↑  
need to write this  
in terms of the  $B_{..}$   
(implicit differentiation)

Recall

$$F_1(x, g(x, y_k), y_k) = F_2(x, g(x, y_k), y_k)$$

$$= F_{k-1}(x, g(x, y_k), y_k) = 0$$

$$\left. \frac{\partial F_i(x, g(x, y_k), y_k)}{\partial y_k} \right|_{(x, y_k) = (a, b_k)} = \sum_{j=1}^{k-1} \boxed{\frac{\partial F_i}{\partial y_j}(x, g(x, y_k), y_k)} \frac{\partial g_j(a, b_k)}{\partial y_k} + \boxed{\frac{\partial F_i}{\partial y_k}(x, g(x, y_k), y_k)}$$

$$\left. \frac{\partial F_i(x, g(x, y_k), y_k)}{\partial y_k} \right|_{(x, y_k) = (a, b_k)} = \sum_{j=1}^{k-1} B_{ij} \frac{\partial g_j(a, b_k)}{\partial y_k} + B_{ik} = 0 \quad \text{for } i=1, \dots, k-1$$

solve for  $\frac{\partial g_i}{\partial y_k}$

System of linear equations

$$\begin{bmatrix} B_{11} & \cdots & B_{1,k-1} \\ \vdots & \ddots & \vdots \\ B_{k-1,1} & \cdots & B_{k-1,k-1} \end{bmatrix} \begin{bmatrix} \frac{\partial g_1}{\partial y_k} \\ \vdots \\ \frac{\partial g_{k-1}}{\partial y_k} \end{bmatrix} = - \begin{bmatrix} B_{1k} \\ \vdots \\ B_{k-1,k} \end{bmatrix}$$

$M^{kk}$        $\det M^{kk} \neq 0$

Cramer's rule.

$$\frac{\partial g_j}{\partial y_k} =$$

$$\frac{\det M_{j,k}^{kk}}{\det M^{kk}}$$

replace the  $j$ th column  
of  $M^{kk}$  with .

$$\begin{bmatrix} B_{1k} \\ \vdots \\ B_{k-1,k} \end{bmatrix}$$
$$\begin{bmatrix} B_{1k} \\ \vdots \\ B_{k-1,k} \end{bmatrix}$$

Substitute into

$$\left. \frac{\partial F_k(x, g(x, y_k), y_k)}{\partial y_k} \right|_{(x, y_k) = (a, b_k)} = \sum_{j=1}^{k-1} B_{kj} \frac{\partial g_j(a, bx)}{\partial y_k} + B_{kk}$$

d to write

Next time finish this and then start integration