

We have jumped ahead all the way to Chapter 6.4 and will definitely return to Chapter 5 later. There are two important algorithms in this class

- Gaussian elimination (row operations)
- Gram-Schmidt orthogonalization (column operations)

and I wanted to cover the second algorithm sooner than later, so there was more time for it to sink in.

an alternative way to write the Gram-Schmidt from class algorithm

substitute q_1 into the definition of t_2 and then perform all the normalization steps at the end.

$$t_1 = a_1$$

$$\|t_1\| = \sqrt{t_1 \cdot t_1}$$

$$\|t_1\|^2 = t_1 \cdot t_1$$

$$q_1 = \frac{t_1}{\|t_1\|}$$

$$t_2 = a_2 - (q_1 \cdot a_2) q_1 \approx a_2 - \left(\frac{t_1 \cdot a_2}{\|t_1\|} \right) \frac{t_1}{\|t_1\|}$$

claim t_2 is perpendicular to q_1

$$\text{so } q_1 \cdot q_1 = 1$$

$$t_2 \cdot q_1 = (a_2 - (q_1 \cdot a_2) q_1) \cdot q_1$$

$$= a_2 \cdot q_1 - (q_1 \cdot a_2) \underbrace{(q_1 \cdot q_1)}_{\text{unit vector}}$$

$$t_2 = a_2 - \frac{t_1 \cdot a_2}{t_1 \cdot t_1} t_1$$

another way to write the same algorithm. Then create the unit vectors at the end...

Example of Gram-Schmidt

matrix with orthonormal columns

upper triangular matrix.

Goal is to factor $A = QR$

4×3 4×3 3×3

factor this matrix

$\in \mathbb{R}^{4 \times 3}$

In general $A \in \mathbb{R}^{m \times n}$ with $m \geq n$ since the columns are independent

$$A = \begin{bmatrix} -1 & 6 & 6 \\ 3 & -8 & 3 \\ 1 & -2 & 6 \\ 1 & -4 & -3 \end{bmatrix}$$

$$A = QR$$

$m \times n$ $m \times n$ $n \times n$

don't do this

Example ...

$$t_1 = \begin{bmatrix} -1 \\ 3 \\ 1 \\ 1 \end{bmatrix}$$

$$\|t_1\| = \sqrt{1 + 9 + 1 + 1} = \sqrt{12}$$

$$q_1 = \frac{1}{\sqrt{12}} \begin{bmatrix} -1 \\ 3 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -1/\sqrt{12} \\ 3/\sqrt{12} \\ 1/\sqrt{12} \\ 1/\sqrt{12} \end{bmatrix}$$

dot prod goes in R

$$t_2 = \begin{bmatrix} 6 \\ -8 \\ -2 \\ -4 \end{bmatrix}$$

$$\frac{1}{\sqrt{12}} \begin{bmatrix} -1 \\ 3 \\ 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 6 \\ -8 \\ -2 \\ -4 \end{bmatrix}$$

dot product

$$\begin{array}{r} -6 \\ -24 \\ -2 \\ -4 \\ \hline -36 \end{array}$$

$$= \frac{1}{12} \left(\begin{bmatrix} -1 \\ 3 \\ 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 6 \\ -8 \\ -2 \\ -4 \end{bmatrix} \right) \begin{bmatrix} -1 \\ 3 \\ 1 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 6 \\ -8 \\ -2 \\ -4 \end{bmatrix} + 3 \begin{bmatrix} -1 \\ 3 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \\ 1 \\ -1 \end{bmatrix}$$

$$q_2 = \frac{1}{\sqrt{12}} \begin{bmatrix} 3 \\ 1 \\ 1 \\ -1 \end{bmatrix}$$

$$t_3 = \begin{bmatrix} 6 \\ 3 \\ 6 \\ -3 \end{bmatrix} - \left(\frac{1}{\sqrt{12}} \begin{bmatrix} -1 \\ 3 \\ 1 \\ 1 \end{bmatrix} \begin{bmatrix} 6 \\ 3 \\ 6 \\ -3 \end{bmatrix} \right) - \left(\frac{1}{\sqrt{12}} \begin{bmatrix} -1 \\ 3 \\ 1 \\ 1 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \\ 1 \\ -1 \end{bmatrix} \right) - \left(\frac{1}{\sqrt{12}} \begin{bmatrix} 3 \\ 1 \\ 1 \\ -1 \end{bmatrix} \begin{bmatrix} 6 \\ 3 \\ 6 \\ -3 \end{bmatrix} \right) - \left(\frac{1}{\sqrt{12}} \begin{bmatrix} 3 \\ 1 \\ 1 \\ -1 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \\ 1 \\ -1 \end{bmatrix} \right)$$

$$\frac{30}{12} \cdot \frac{3 \cdot 5 \cdot 2}{3 \cdot 2 \cdot 2}$$

$$= \begin{bmatrix} 6 \\ 3 \\ 6 \\ -3 \end{bmatrix} - \frac{1}{\sqrt{12}} \begin{bmatrix} -1 \\ 3 \\ 1 \\ 1 \end{bmatrix} 6 - \frac{1}{\sqrt{12}} \begin{bmatrix} -1 \\ 3 \\ 1 \\ 1 \end{bmatrix} 30 - \frac{1}{\sqrt{12}} \begin{bmatrix} 3 \\ 1 \\ 1 \\ -1 \end{bmatrix} 3$$

dot products

$$\begin{array}{r} -6 \\ 9 \\ 6 \\ -3 \\ \hline 6 \end{array}$$

$$= \begin{bmatrix} 6 \\ 3 \\ 6 \\ -3 \end{bmatrix} - \frac{1}{\sqrt{12}} \left(\begin{bmatrix} -1 \\ 3 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 15 \\ 5 \\ 5 \\ -5 \end{bmatrix} \right)$$

dot prod

$$\begin{array}{r} 18 \\ 3 \\ 6 \\ 3 \\ \hline 30 \end{array}$$

$$= \begin{bmatrix} 6 \\ 3 \\ 6 \\ -3 \end{bmatrix} - \begin{bmatrix} 7 \\ 4 \\ 3 \\ -2 \end{bmatrix} = \begin{bmatrix} -1 \\ -1 \\ 3 \\ -1 \end{bmatrix}$$

$$f_3 = \frac{1}{\sqrt{12}} \begin{bmatrix} -1 \\ -1 \\ 3 \\ -1 \end{bmatrix}$$

$$Q = \begin{bmatrix} | & | & | \\ f_1 & f_2 & f_3 \\ | & | & | \end{bmatrix}$$

$$R = \begin{bmatrix} ? \\ ? \\ ? \end{bmatrix}$$