

M 3

output  $\downarrow$   
 $A \in \mathbb{R}^{m \times n}$  ← input  $A^T \in \mathbb{R}^{n \times m}$  ← input

Let  $A$  be an  $m \times n$  matrix. The orthogonal complement of the row space of  $A$  is the null space of  $A$ , and the orthogonal complement of the column space of  $A$  is the null space of  $A^T$ :

↔ equivalent ↔

(Row  $A$ )<sup>⊥</sup> = Nul  $A$  and (Col  $A$ )<sup>⊥</sup> = Nul  $A^T$

$Col A = \{ Ax : x \in \mathbb{R}^n \} \subseteq \mathbb{R}^m$

$Nul A^T = \{ y : A^T y = 0 \} \subseteq \mathbb{R}^m$

If  $w \in Col A$  that means  $w = Ax$  for some  $x \in \mathbb{R}^n$

$H^\perp = \{ z : z \cdot w = 0 \text{ for all } w \in H \}$

$(Col A)^\perp = \{ z : z \cdot w = 0 \text{ for all } w \in Col A \}$

$\{ z : z \cdot Ax = 0 \text{ for all } x \in \mathbb{R}^n \}$

$\{ z : x \cdot A^T z = 0 \text{ for all } x \in \mathbb{R}^n \}$

Note

- $z \cdot Ax = 0$
- $Ax \cdot z = 0$
- $(Ax)^T z = 0$
- $x^T A^T z = 0$
- $x \cdot A^T z = 0$

all mean the same thing.

Claim:  $A^T z = 0$  is equivalent to  $x \cdot A^T z = 0$  for all  $x \in \mathbb{R}^n$  if and only if means the same thing as

" $\Rightarrow$ "  $A^T z = 0$  implies  $x \cdot A^T z = 0$  for all  $x \in \mathbb{R}^n$  is easy...

" $\Leftarrow$ " Suppose  $x \cdot A^T z = 0$  for all  $x \in \mathbb{R}^n$ . Why is  $A^T z = 0$ ?

what vector  $A^T z$  could be perpendicular to all other vectors?

what vector is perpendicular to itself?  $x = A^T z$  and plug it in..

$A^T z \cdot A^T z = 0$  which means  $\|A^T z\|^2 = 0$  so  $A^T z = 0$ .

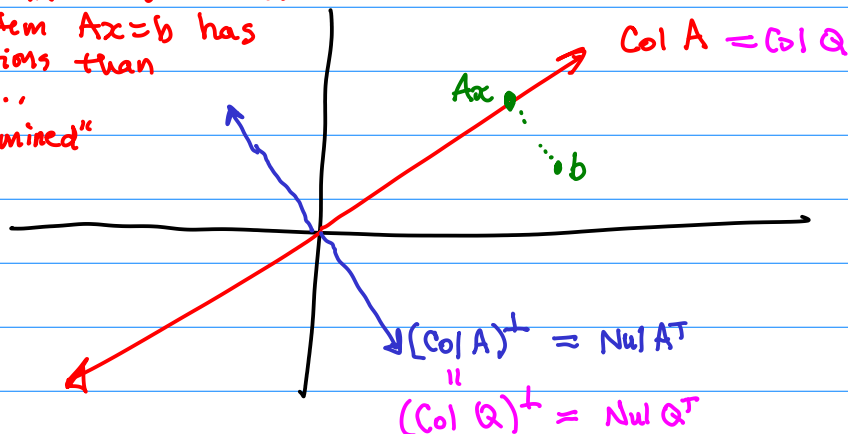
Therefore

$(Col A)^\perp = \{ z : x \cdot A^T z = 0 \text{ for all } x \in \mathbb{R}^n \}$   
 $= \{ z : A^T z = 0 \} = Nul A^T$

let  $A = QR$

Consider  $A \in \mathbb{R}^{m \times n}$  and  $m > n$   
 so the system  $Ax = b$  has more equations than unknowns..  
 "overdetermined"

Idea:  
 minimize  $\|Ax - b\|$



$(Col Q)^\perp = Nul Q^T$

What's left is to solve some least squares problems:

$Ax=b$  overdetermined, factor  $A=QR$

$$QRx=b$$

$$Q^T QRx = Q^T b$$

$$Rx = Q^T b$$

$$Rx = Q^T b$$

← solve this for  $x$  and that  $x$  turns out to minimize  $\|Ax-b\|$ .

EXAMPLE

so  $Ax=b$  is overdetermined

$$16. A = \begin{bmatrix} 1 & -1 \\ 1 & 4 \\ 1 & -1 \\ 1 & 4 \end{bmatrix} = \begin{bmatrix} 1/2 & -1/2 \\ 1/2 & 1/2 \\ 1/2 & -1/2 \\ 1/2 & 1/2 \end{bmatrix} \begin{bmatrix} 2 & 3 \\ 0 & 5 \end{bmatrix}, b = \begin{bmatrix} -1 \\ 6 \\ 5 \\ 7 \end{bmatrix}$$

Solve  $Rx = Q^T b$

$$\frac{1}{2} \begin{bmatrix} 1 & 1 & 1 & 1 \\ -1 & 1 & -1 & 1 \end{bmatrix} \begin{bmatrix} -1 \\ 6 \\ 5 \\ 7 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 17 \\ 9 \end{bmatrix} = \begin{bmatrix} 17/2 \\ 9/2 \end{bmatrix}$$

$$\begin{array}{r} 3 \\ 17 \\ 5 \\ \hline 45 \\ -27 \\ \hline 58 \end{array}$$

$$\begin{bmatrix} 2 & 3 \\ 0 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 17/2 \\ 9/2 \end{bmatrix} \quad \left. \begin{array}{l} 2x_1 + 3x_2 = 17/2 \\ 5x_2 = 9/2 \end{array} \right\}$$

$$x_2 = \frac{9}{10} \quad x_1 = \frac{1}{2} \left( \frac{17}{2} - 3x_2 \right) = \frac{1}{2} \left( \frac{17}{2} - \frac{27}{10} \right) = \frac{1}{2} \frac{58}{10} = \frac{29}{10}$$

Thus  $x = \begin{bmatrix} 29/10 \\ 9/10 \end{bmatrix}$  minimizes  $\|Ax-b\|$ .