

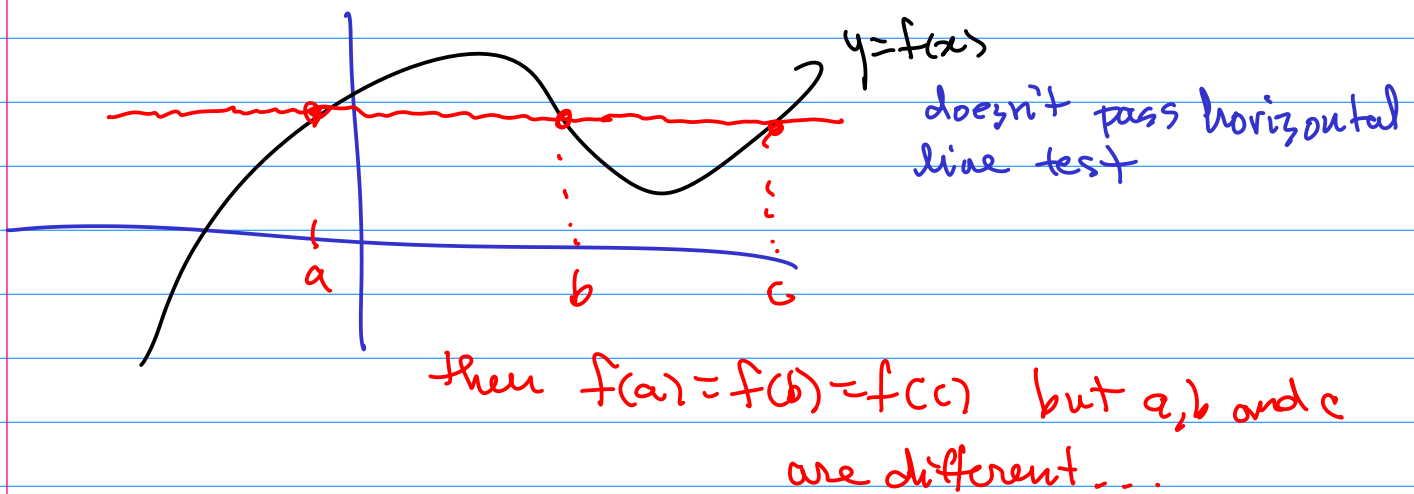
The Invertible Matrix Theorem

Let A be a square $n \times n$ matrix. Then the following statements are equivalent. That is, for a given A , the statements are either all true or all false.

- ✓ a. A is an invertible matrix.
- ✓ b. A is row equivalent to the $n \times n$ identity matrix. *reduced echelon form of A .*
- ✓ c. A has n pivot positions. *↔ pivot in every row means no row is zero.*
- ✓ d. The equation $Ax = \mathbf{0}$ has only the trivial solution. *↔ free variable so less pivots... not enough pivots*
- ✓ e. The columns of A form a linearly independent set. *↔ if not, there are free variables*
- ✓ f. The linear transformation $x \mapsto Ax$ is one-to-one. *↔ the only solution to $Ax = \mathbf{0}$ is the trivial solution*
- g. The equation $Ax = \mathbf{b}$ has at least one solution for each \mathbf{b} in \mathbb{R}^n .
- h. The columns of A span \mathbb{R}^n .
- i. The linear transformation $x \mapsto Ax$ maps \mathbb{R}^n onto \mathbb{R}^n .
- j. There is an $n \times n$ matrix C such that $CA = I$.
- k. There is an $n \times n$ matrix D such that $AD = I$.
- l. A^T is an invertible matrix. *↔ talk about later...*

Same

If $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is one-to-one does this mean it's invertible... *the horizontal line test for invertibility*



Clear if f is not one-to-one then it's not invertible...

Condition of $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$ being onto

Note that not only does f have to be one-to-one but the range of f has to be all of \mathbb{R}^n , so any $y \in \mathbb{R}^n$ can be seen as the output $y = f(x)$ for some $x \in \mathbb{R}^n$.

If one-to-one that means for every $x \neq w$ that $f(x) \neq f(w)$.

$$Ax \neq Aw \text{ for every } x \neq w \dots$$

$$Ax - Aw \neq 0 \text{ for every } x \neq w$$

linearity

$$A(x-w) \neq 0 \text{ for every } x \neq w$$

Thus the only solution to $Ax = 0$ is $x = 0$. because anything not equal zero can be written as $x-w$ where $x \neq w$.

I.e. the only time $A(x-w) = 0$ is when $x = w$.

g. The equation $Ax = b$ has at least one solution for each b in \mathbb{R}^n . ^{the only}

This says that $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is onto \mathbb{R}^n . Thus we can solve $Av_1 = e_1, \dots, Av_n = e_n$

$$A^{-1} = [v_1 | v_2 | \dots | v_n]$$

It follows that

column representations
of matrix mult...

$$AA^{-1} = A \left[v_1 | v_2 | \dots | v_n \right] = \left[Av_1 | Av_2 | \dots | Av_n \right]$$
$$\approx \left[e_1 | e_2 | \dots | e_n \right] = I$$

make this...

If $AA^{-1} = I$ does it follow that $A^{-1}A = I$?

In general $AB \neq BA$. Also if by chance

$AB = I$ it's not necessary that $BA = I$.

However, if $A \in \mathbb{R}^{n \times n}$ then it's true that $BA = I$ also...

Given...

$$AA^{-1} = I$$

$$AA^{-1}A = IA = A$$

$$A(A^{-1}A) = A$$

trying to show (understand why)

$$A^{-1}A = I$$

need to know A is one to one... to
conclude this... I only know A is
onto...

- ① If A is onto then you can solve $Ax = b$ for every b .
- ② this means there is a pivot in each row of A .
- ③ If there is a pivot in every row and A is square this means there is a pivot in every column.

④ If there is a pivot in every column there are no free variables.

⑤ That means A is one-to-one.

Chapter
2.5

We have examples of finding LU already... but not very many of using it to solve $Ax=b$.

Solve $Ax=b$ where $A =$

$$1. A = \begin{bmatrix} 3 & -7 & -2 \\ -3 & 5 & 1 \\ 6 & -4 & 0 \end{bmatrix}, b = \begin{bmatrix} -7 \\ 5 \\ 2 \end{bmatrix}$$

$$A = \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 2 & -5 & 1 \end{bmatrix}}_L \begin{bmatrix} 3 & -7 & -2 \\ 0 & -2 & -1 \\ 0 & 0 & -1 \end{bmatrix}_U$$

$$Ax=b$$

$$LUx=b$$

$$y=Ux$$

$$\begin{cases} Ly=b \\ Ux=y \end{cases}$$

solve this system of systems..

First solve $Ly=b$:

$$\begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 2 & -5 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} -7 \\ 5 \\ 2 \end{bmatrix}$$

By substitution

$$y_1 = -7$$

$$-y_1 + y_2 = 5$$

$$2y_1 - 5y_2 + y_3 = 2$$

$$y_1 = -7$$

$$y_2 = 5 + y_1 = 12 - 2$$

$$y_3 = 2 - 2y_1 + 5y_2$$

$$y_3 = 2 + 14 \sim 10 = 6$$

$$y = \begin{bmatrix} -7 \\ -2 \\ 6 \end{bmatrix}$$

↗
~~Makes me~~
~~scared...~~ ok

Next solve $Ux=y$ by substitution...