

The book writes the Gram-Schmidt without introducing the unit vectors  $q$ . This avoids square roots in the algorithm, but make the matrix  $Q$  and  $R$  more difficult to identify

### The Gram-Schmidt Process

Given a basis  $\{x_1, \dots, x_p\}$  for a nonzero subspace  $W$  of  $\mathbb{R}^n$ , define

$$\begin{aligned}
 v_1 &= x_1 \\
 v_2 &= x_2 - \frac{x_2 \cdot v_1}{v_1 \cdot v_1} v_1 \\
 v_3 &= x_3 - \frac{x_3 \cdot v_1}{v_1 \cdot v_1} v_1 - \frac{x_3 \cdot v_2}{v_2 \cdot v_2} v_2 \\
 &\vdots \\
 v_p &= x_p - \frac{x_p \cdot v_1}{v_1 \cdot v_1} v_1 - \frac{x_p \cdot v_2}{v_2 \cdot v_2} v_2 - \dots - \frac{x_p \cdot v_{p-1}}{v_{p-1} \cdot v_{p-1}} v_{p-1}
 \end{aligned}$$

we identified  $q_1 = \frac{v_1}{\|v_1\|}$  unit vector

Then  $\{v_1, \dots, v_p\}$  is an orthogonal basis for  $W$ . In addition

$$\text{Span}\{v_1, \dots, v_k\} = \text{Span}\{x_1, \dots, x_k\} \quad \text{for } 1 \leq k \leq p \quad (1)$$

start with  $v$ 's since  $x$ 's are usually the variables rather than columns of  $A$ .

Let  $\{v_1, v_2, \dots, v_n\}$  be a basis for  $W$ . Then

columns of  $A$

$$z_1 = v_1$$

$$z_2 = v_2 - (q_1 \cdot v_2) q_1$$

$$z_3 = v_3 - (q_1 \cdot v_3) q_1 - (q_2 \cdot v_3) q_2$$

⋮

$$q_1 = \frac{z_1}{\|z_1\|}$$

$$q_2 = \frac{z_2}{\|z_2\|}$$

$$q_3 = \frac{z_3}{\|z_3\|}$$

⋮

columns of  $Q$

$$z_n = v_n - (q_1 \cdot v_n) q_1 - (q_2 \cdot v_n) q_2 - \dots - (q_{n-1} \cdot v_n) q_{n-1}$$

work these examples!

$$q_n = \frac{z_n}{\|z_n\|}$$

Chapter 6.5

3.  $\begin{bmatrix} 2 \\ -5 \\ 1 \end{bmatrix}, \begin{bmatrix} 4 \\ -1 \\ 2 \end{bmatrix}$

10.  $\begin{bmatrix} -1 & 6 & 6 \\ 3 & -8 & 3 \\ 1 & -2 & 6 \\ 1 & -4 & -3 \end{bmatrix}$

next time...

first  
↓

$$3. \begin{bmatrix} 2 \\ -5 \\ 1 \end{bmatrix}, \begin{bmatrix} 4 \\ -1 \\ 2 \end{bmatrix}$$

$v_1$                    $v_2$

$$\|z_1\| = \sqrt{2^2 + (-5)^2 + 1^2} = \sqrt{4 + 25 + 1} = \sqrt{30}$$

$$z_1 = \begin{bmatrix} 2 \\ -5 \\ 1 \end{bmatrix}$$

$$q_1 = \frac{z_1}{\|z_1\|} = \frac{1}{\sqrt{30}} \begin{bmatrix} 2 \\ -5 \\ 1 \end{bmatrix}$$

need to know this coefficient to find R

$$z_2 = v_2 - (q_1 \cdot v_2) q_1 = \begin{bmatrix} 4 \\ -1 \\ 2 \end{bmatrix} - \left( \frac{1}{\sqrt{30}} \begin{bmatrix} 2 \\ -5 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 4 \\ -1 \\ 2 \end{bmatrix} \right) \frac{1}{\sqrt{30}} \begin{bmatrix} 2 \\ -5 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 4 \\ -1 \\ 2 \end{bmatrix} - \left( \frac{1}{\sqrt{30}} (8 + 5 + 2) \right) \frac{1}{\sqrt{30}} \begin{bmatrix} 2 \\ -5 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ -1 \\ 2 \end{bmatrix} - \frac{15}{\sqrt{30}} \frac{1}{\sqrt{30}} \begin{bmatrix} 2 \\ -5 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 4 \\ -1 \\ 2 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 2 \\ -5 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 3/2 \\ 3/2 \end{bmatrix}$$

$$q_2 = \frac{z_2}{\|z_2\|} = \frac{1}{\frac{1}{2}\sqrt{54}} \begin{bmatrix} 3 \\ 3/2 \\ 3/2 \end{bmatrix} = \frac{1}{\sqrt{54}} \begin{bmatrix} 6 \\ 3 \\ 3 \end{bmatrix}$$

This is one of the coefficients in R.

Turning this into a unit vector is the same as turning any multiple into a unit vector, so one could use  $\begin{bmatrix} 6 \\ 3 \\ 3 \end{bmatrix}$  to avoid

the fractions. However

$$\left\| \begin{bmatrix} 3 \\ 3/2 \\ 3/2 \end{bmatrix} \right\| = \frac{1}{2} \left\| \begin{bmatrix} 6 \\ 3 \\ 3 \end{bmatrix} \right\| = \frac{1}{2} \sqrt{36 + 9 + 9} = \frac{1}{2} \sqrt{54}$$

$$\frac{36}{45} = \frac{4}{5}$$

Thus starting with the vectors

$$\begin{bmatrix} 2 \\ -5 \\ 1 \end{bmatrix}, \begin{bmatrix} 4 \\ -1 \\ 2 \end{bmatrix}$$

I used Gram-Schmidt to obtain

$$\frac{1}{\sqrt{30}} \begin{bmatrix} 2 \\ -5 \\ 1 \end{bmatrix}, \frac{1}{\sqrt{54}} \begin{bmatrix} 6 \\ 3 \\ 3 \end{bmatrix}$$

$$A = \begin{bmatrix} 2 & 4 \\ -5 & -1 \\ 1 & 2 \end{bmatrix}$$

$$Q = \begin{bmatrix} 2/\sqrt{30} & 6/\sqrt{54} \\ -5/\sqrt{30} & 3/\sqrt{54} \\ 1/\sqrt{30} & 3/\sqrt{54} \end{bmatrix}$$

These columns are a linear combination of the columns of A.

Since the column operations were reversible, then the columns of A are also linear combinations of the columns of Q.

Therefore  $\text{col } A = \text{col } Q$

Claim:  $A = QR$  for some upper triangular matrix R.  
↑ correspond to the reverse of the column operations used to obtain Q from A.

Recall when we did row operations for Gaussian elimination we ended up with  $A = LU$

↑ corresponded to the reverse of the row operations used to obtain U from A.

Note column operations are mult on the right by R  
row operations are mult on the left by L

$$z_1 = v_1 = \|z_1\| q_1$$

$$q_1 = \frac{z_1}{\|z_1\|}$$

$$z_2 = v_2 - (q_1 \cdot v_2) q_1$$

$$q_2 = \frac{z_2}{\|z_2\|}$$

$$v_2 = z_2 + (q_1 \cdot v_2) q_1$$

$$v_2 = \|z_2\| q_2 + (q_1 \cdot v_2)$$

Thus :

$$v_1 = \|z_1\| q_1$$

$$v_2 = (q_1 \cdot v_2) q_1 + \|z_2\| q_2$$

write this as matrix multiplication

$$A = \begin{bmatrix} | & | \\ v_1 & v_2 \\ | & | \end{bmatrix} = \begin{bmatrix} | & | \\ \|z_1\| q_1 & (q_1 \cdot v_2) q_1 + \|z_2\| q_2 \\ | & | \end{bmatrix} = \begin{bmatrix} | & | \\ q_1 & q_2 \\ | & | \end{bmatrix} \underbrace{\begin{bmatrix} \|z_1\| & q_1 \cdot v_2 \\ 0 & \|z_2\| \end{bmatrix}}_R$$

$$R = \begin{bmatrix} \|z_1\| & q_1 \cdot v_2 \\ 0 & \|z_2\| \end{bmatrix} = \begin{bmatrix} \sqrt{30} & 15/\sqrt{30} \\ 0 & \frac{1}{2}\sqrt{54} \end{bmatrix}$$

$$\frac{15}{\sqrt{30}} = \frac{15\sqrt{30}}{30} = \frac{1}{2}\sqrt{30}$$

Therefore  $A = QR$  where ...

$$\begin{bmatrix} 2 & 4 \\ -5 & -1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 2/\sqrt{30} & 6/\sqrt{54} \\ -5/\sqrt{30} & 3/\sqrt{54} \\ 1/\sqrt{30} & 3/\sqrt{54} \end{bmatrix} \begin{bmatrix} \sqrt{30} & \frac{1}{2}\sqrt{30} \\ 0 & \frac{1}{2}\sqrt{54} \end{bmatrix} \quad \checkmark$$

Note the columns of  $Q$  are orthonormal vectors...

$$q_1 \cdot q_1 = 1, \quad q_1 \cdot q_2 = 0, \quad q_2 \cdot q_2 = 1$$

Thus  $Q^T Q = I$

← explain this more next time... note  $Q$  is not invertible since not square, but can undo its effects by mult. on left with  $Q^T$ .