

Chapter 1.7

- No free variables
unique soln to $Ax=0$

An indexed set of vectors $\{v_1, \dots, v_p\}$ in \mathbb{R}^n is said to be linearly independent if the vector equation

$$x_1 v_1 + x_2 v_2 + \dots + x_p v_p = 0 \quad Ax=0$$

has only the trivial solution. The set $\{v_1, \dots, v_p\}$ is said to be linearly dependent if there exist weights c_1, \dots, c_p , not all zero, such that

$$c_1 v_1 + c_2 v_2 + \dots + c_p v_p = 0 \quad (2)$$

- free variables
- $Ax=0$ has an infinite # of solutions

$$A = \left[\begin{array}{c|c|c|c} v_1 & v_2 & \dots & v_p \end{array} \right] \quad Ax = \left[\begin{array}{c|c|c|c} v_1 & v_2 & \dots & v_p \end{array} \right] \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = x_1 v_1 + x_2 v_2 + \dots + x_p v_p$$

Example: $v_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}$, $v_2 = \begin{bmatrix} 2 \\ 1 \\ 0 \\ 0 \end{bmatrix}$, $v_3 = \begin{bmatrix} 0 \\ 1 \\ -6 \\ 7 \end{bmatrix}$, $p=3$

$v_1, v_2, v_3 \in \mathbb{R}^4$
 $n=4$

columns variables input

rows correspond to output

rows columns

$$A = \begin{bmatrix} 1 & 2 & 0 \\ 2 & 1 & 1 \\ 3 & 0 & -6 \\ 4 & 0 & 7 \end{bmatrix} \in \mathbb{R}^{4 \times 3}$$

Consider $Ax=0$

- ① There is exactly one solution since $x=0$ is always a solution then that one solution is $x=0$
- ② There are infinitely many solutions.

Suppose $Ax=0$ had at least two solutions.

call one solution a and the other b .
 One of those solutions is not equal to zero.
 For definiteness suppose $a \neq 0$.
 Now consider $c = 2a$. Then $c \neq a$ since $a \neq 0$
 consider $d = 3a$ Then $d \neq a$ and $d \neq c$ since $a \neq 0$.

Claim c, d are both solutions.

Characterization of Linearly Dependent Sets

An indexed set $S = \{v_1, \dots, v_p\}$ of two or more vectors is linearly dependent if and only if at least one of the vectors in S is a linear combination of the others. In fact, if S is linearly dependent and $v_1 \neq \mathbf{0}$, then some v_j (with $j > 1$) is a linear combination of the preceding vectors, v_1, \dots, v_{j-1} .

The idea with linear dependence is to study the solutions of $Ax=0$, or in other words

$$x_1 v_1 + x_2 v_2 + \dots + x_p v_p = \mathbf{0}$$

Suppose $x_p \neq 0$ then I could solve for v_p as

$$v_p = -\frac{1}{x_p} (x_1 v_1 + x_2 v_2 + \dots + x_{p-1} v_{p-1})$$

Example $S = \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right\}$

$$Ax = \begin{bmatrix} 1 & 0 \\ 2 & 0 \\ 3 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \mathbf{0}$$

$$x = \begin{bmatrix} 0 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} x_2$$

$$v_1 x_1 + v_2 x_2 = \mathbf{0}$$

$v_2 =$ combination of the other vectors

$$\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = 0 \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

If a set $S = \{v_1, \dots, v_p\}$ in \mathbb{R}^n contains the zero vector, then the set is linearly dependent.

If a set contains more vectors than there are entries in each vector, then the set is linearly dependent. That is, any set $\{v_1, \dots, v_p\}$ in \mathbb{R}^n is linearly dependent if $p > n$.

$$A = \begin{bmatrix} | & | & | & | \\ v_1 & v_2 & \dots & v_p \\ | & | & | & | \end{bmatrix} \in \mathbb{R}^{n \times p}$$

\swarrow rows
 \searrow columns

There can be at most n pivots, because there are n rows. If there are more columns than pivots there must be free variables.

Why row \times columns and not the other way...

$$f(x) = Ax \qquad g(x) = Bx$$

$$(f \circ g)(x) = f(g(x)) = f(Bx) = ABx$$

$$f: \mathbb{R}^p \rightarrow \mathbb{R}^n \quad \text{and} \quad g: \mathbb{R}^m \rightarrow \mathbb{R}^p$$

$$A \in \mathbb{R}^{n \times p} \qquad B \in \mathbb{R}^{p \times m}$$

$$\begin{array}{ccc}
 A & B & x \\
 \underbrace{m \times p} & \underbrace{p \times m} & m
 \end{array}$$