

Find the reduced echelon form

$$A = \begin{bmatrix} -2 & 4 & -2 & -4 \\ 2 & -6 & -3 & 1 \\ -3 & 8 & 2 & -3 \end{bmatrix}$$

$$r_2 \leftarrow r_2 + r_1$$

$$r_3 \leftarrow r_3 - \frac{3}{2}r_1$$

row col.

$$\begin{bmatrix} -2 & 4 & -2 & -4 \\ 0 & -2 & -5 & -3 \\ 0 & 2 & 5 & 3 \end{bmatrix}$$

$$r_3 \leftarrow r_3 + r_2$$

Practice LU factorization

echelon form

$$U = \begin{bmatrix} -2 & 4 & -2 & -4 \\ 0 & -2 & -5 & -3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$L = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 3/2 & -1 & 1 \end{bmatrix}$$

$$r_1 \leftarrow r_1 + 2r_2$$

$$\begin{bmatrix} -2 & 0 & -12 & -10 \\ 0 & -2 & -5 & -3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$r_1 \leftarrow -\frac{1}{2}r_1$$

$$r_2 \leftarrow -\frac{1}{2}r_2$$

reduced echelon form

$$\begin{bmatrix} 1 & 0 & 6 & 5 \\ 0 & 1 & 5/2 & 3/2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

P P F F
 x_1 x_2 x_3 x_4

To solve $Ax=0$ is the same as solving

$$\begin{bmatrix} 1 & 0 & 6 & 5 \\ 0 & 1 & 5/2 & 3/2 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = 0$$

$$x_1 + 6x_3 + 5x_4 = 0$$

$$x_2 + 5/2x_3 + 3/2x_4 = 0$$

Solve for pivot variables in terms of free variables

$$x_1 = -6x_3 - 5x_4$$

$$x_2 = -5/2 x_3 - 3/2 x_4$$

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -6x_3 - 5x_4 \\ -5/2 x_3 - 3/2 x_4 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -6 \\ -5/2 \\ 1 \\ 0 \end{bmatrix} x_3 + \begin{bmatrix} -5 \\ -3/2 \\ 0 \\ 1 \end{bmatrix} x_4$$

all the solutions to $Ax=0$.

$$\text{Nul } A = \left\{ x : Ax=0 \right\} = \left\{ \begin{bmatrix} -6 \\ -5/2 \\ 1 \\ 0 \end{bmatrix} x_3 + \begin{bmatrix} -5 \\ -3/2 \\ 0 \\ 1 \end{bmatrix} x_4 ; x_3, x_4 \in \mathbb{R} \right\}$$

$$= \text{span} \left\{ \begin{bmatrix} -6 \\ -5/2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -5 \\ -3/2 \\ 0 \\ 1 \end{bmatrix} \right\} = \text{Col} \begin{bmatrix} -6 & -5 \\ -5/2 & -3/2 \\ 1 & 0 \\ 0 & 1 \end{bmatrix} \quad \text{this is a span}$$

each vector corresponds to a different free variable therefore the vectors are independent (because where the 1's and 0's are in relation to the free vbls).

A basis for $\text{Nul } A$ is $\left\{ \begin{bmatrix} -6 \\ -5/2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -5 \\ -3/2 \\ 0 \\ 1 \end{bmatrix} \right\}$.

Chapt 4.3

Let H be a subspace of a vector space V . A set of vectors B in V is a **basis** for H if

- (i) B is a linearly independent set, and
- (ii) the subspace spanned by B coincides with H ; that is,

$$H = \text{Span } B$$

$$A = \begin{bmatrix} -2 & 4 & -2 & -4 \\ 2 & -6 & -3 & 1 \\ -3 & 8 & 2 & -3 \end{bmatrix}$$

pivot columns

$$\begin{array}{cccc} P & P & F & F \\ x_1 & x_2 & x_3 & x_4 \\ \begin{bmatrix} 1 & 0 & 6 & 5 \\ 0 & 1 & 5/2 & 3/2 \\ 0 & 0 & 0 & 0 \end{bmatrix} \end{array}$$

reduced echelon form

How to find a basis for $\text{Col } A$?

Any dependency relation between the columns of the echelon form is also a dependency relation between the columns of A .

Every column of the (reduced) echelon form can be written as a linear combination of the pivot columns.

So the pivot columns of A form a basis for $\text{Col } A$.

$$\text{Basis of Col } A \text{ is } \left\{ \begin{bmatrix} -2 \\ 2 \\ -3 \end{bmatrix}, \begin{bmatrix} 4 \\ -6 \\ 8 \end{bmatrix} \right\}.$$

New subspace...

$$\text{row } A = \text{Col } A^T = \left\{ A^T z : z \in \mathbb{R}^m \right\} \subseteq \mathbb{R}^n$$

$$= \text{span} \left\{ \begin{bmatrix} -2 \\ 4 \\ -2 \\ -4 \end{bmatrix}, \begin{bmatrix} 2 \\ -6 \\ -3 \\ 1 \end{bmatrix}, \begin{bmatrix} -3 \\ 8 \\ 2 \\ -3 \end{bmatrix} \right\}$$

$$\begin{bmatrix} -2 & 4 & -2 & -4 \\ 2 & -6 & -3 & 1 \\ -3 & 8 & 2 & -3 \end{bmatrix}^T = \begin{bmatrix} -2 & 2 & -3 \\ 4 & -6 & 8 \\ -2 & -3 & 2 \\ -4 & 1 & -3 \end{bmatrix}$$

One idea perform row operations on A^T to identify the basis of $\text{Col } A^T$.

$$A = \begin{bmatrix} -2 & 4 & -2 & -4 \\ 2 & -6 & -3 & 1 \\ -3 & 8 & 2 & -3 \end{bmatrix}$$

pivot columns

$$\begin{array}{cccc} P & P & F & F \\ x_1 & x_2 & x_3 & x_4 \\ \begin{bmatrix} 1 & 0 & 6 & 5 \\ 0 & 1 & 5/2 & 3/2 \\ 0 & 0 & 0 & 0 \end{bmatrix} \end{array}$$

reduced echelon form

Since row operations are invertible, then

$$\text{row} \begin{bmatrix} -2 & 4 & -2 & -4 \\ 2 & -6 & -3 & 1 \\ -3 & 8 & 2 & -3 \end{bmatrix} = \text{row} \begin{bmatrix} 1 & 0 & 6 & 5 \\ 0 & 1 & 5/2 & 3/2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\text{basis for row } A = \left\{ \begin{bmatrix} 1 \\ 0 \\ 6 \\ 5 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 5/2 \\ 3/2 \end{bmatrix} \right\}$$

these rows form a lin indep. spanning set

One WARNING note that ...

$$\text{col} \begin{bmatrix} -2 & 4 & -2 & -4 \\ 2 & -6 & -3 & 1 \\ -3 & 8 & 2 & -3 \end{bmatrix} \neq \text{col} \begin{bmatrix} 1 & 0 & 6 & 5 \\ 0 & 1 & 5/2 & 3/2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Remark: Just like a linear function can be represented by a matrix, so a subspace can be represented by the column space of a matrix.

The Invertible Matrix Theorem

Let A be a square $n \times n$ matrix. Then the following statements are equivalent, that is, for a given A , the statements are either all true or all false.

- a. A is an invertible matrix.
- b. A is row equivalent to the $n \times n$ identity matrix.
- c. A has n pivot positions.
- d. The equation $A\mathbf{x} = \mathbf{0}$ has only the trivial solution.
- e. The columns of A form a linearly independent set.
- f. The linear transformation $\mathbf{x} \mapsto A\mathbf{x}$ is one-to-one.
- g. The equation $A\mathbf{x} = \mathbf{b}$ has at least one solution for each \mathbf{b} in \mathbb{R}^n .
- h. The columns of A span \mathbb{R}^n .
- i. The linear transformation $\mathbf{x} \mapsto A\mathbf{x}$ maps \mathbb{R}^n onto \mathbb{R}^n .
- j. There is an $n \times n$ matrix C such that $CA = I$.
- k. There is an $n \times n$ matrix D such that $AD = I$.
- l. A^T is an invertible matrix.
- m. The columns of A form a basis of \mathbb{R}^n .
- n. $\text{Col } A = \mathbb{R}^n = \{A\mathbf{x} : \mathbf{x} \in \mathbb{R}^n\}$
- o. $\text{rank } A = n$
- p. $\dim \text{Nul } A = 0$
- q. $\text{Nul } A = \{\mathbf{0}\} = \{\mathbf{x} : A\mathbf{x} = \mathbf{0}\}$

The Unique Representation Theorem

Let $\mathcal{B} = \{\mathbf{b}_1, \dots, \mathbf{b}_n\}$ be a basis for a vector space V . Then for each \mathbf{x} in V , there exists a unique set of scalars c_1, \dots, c_n such that

$$\mathbf{x} = c_1 \mathbf{b}_1 + \dots + c_n \mathbf{b}_n \quad (1)$$

If \mathcal{B} is a basis for V then

$V = \text{span } \mathcal{B}$ and \mathcal{B} is linearly independent

Let

$$\mathcal{B} = \begin{bmatrix} \vdots & \vdots & \vdots & \vdots \\ \mathbf{b}_1 & \mathbf{b}_2 & \dots & \mathbf{b}_n \\ \vdots & \vdots & \vdots & \vdots \end{bmatrix}$$

Equivalently

$V = \text{col } \mathcal{B}$ and $\text{Nul } \mathcal{B} = \{\mathbf{0}\}$,

$\mathbf{x} = c_1 \mathbf{b}_1 + \dots + c_n \mathbf{b}_n$ can be written $\mathbf{x} = \mathcal{B} \mathbf{c}$ where $\mathbf{c} = \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix}$

If this representation of \mathbf{x} were not unique there would be a vector $\mathbf{d} \in \mathbb{R}^n$ such that also $\mathbf{x} = \mathcal{B} \mathbf{d}$,

$$\mathbf{0} = \mathbf{x} - \mathbf{x} = \mathcal{B} \mathbf{c} - \mathcal{B} \mathbf{d} = \mathcal{B} (\mathbf{c} - \mathbf{d}) \quad \text{so} \quad \mathbf{c} - \mathbf{d} \in \text{Nul } \mathcal{B}$$

thus $\mathbf{c} - \mathbf{d} = \mathbf{0}$ and so $\mathbf{c} = \mathbf{d}$.

Therefore the \mathbf{c} such that $\mathbf{x} = \mathcal{B} \mathbf{c}$ is unique...

Let $V \subseteq \mathbb{R}^m$ be a subspace, and

$B = \{b_1, b_2, \dots, b_n\}$ be a basis of V and

$C = \{c_1, c_2, \dots, c_n\}$ be another basis of V .

Since the dimension of the subspace is well defined, both these basis have the same number of vectors and $\dim V = n$.

Talk about the connection between the two basis next time. That is, the change of basis matrix.