

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 4 & 5 \\ 0 & 0 & 6 \end{bmatrix}$$

$$\det A = 1 \cdot 4 \cdot 6 = 24$$

$$\det(A - \lambda I) = \det \begin{bmatrix} 1-\lambda & 2 & 3 \\ 0 & 4-\lambda & 5 \\ 0 & 0 & 6-\lambda \end{bmatrix} = (1-\lambda)(4-\lambda)(6-\lambda) = 0$$

therefore  $\lambda = 1$  or  $4$  or  $6$ .

Now find  $x \neq 0$  in  $\text{Nul}(A - \lambda I)$  for each  $\lambda$

$$\lambda = 1 \quad A - \lambda I = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 4 & 5 \\ 0 & 0 & 6 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 2 & 3 \\ 0 & 3 & 5 \\ 0 & 0 & 5 \end{bmatrix}$$

Find reduced row echelon form to solve  $(A - \lambda I)x = 0$ .

$$\begin{bmatrix} 0 & 2 & 3 \\ 0 & 3 & 5 \\ 0 & 0 & 5 \end{bmatrix}$$

$$r_2 \leftarrow r_2 - \frac{3}{2}r_1$$

$$\begin{bmatrix} 0 & 2 & 3 \\ 0 & 0 & \frac{1}{2} \\ 0 & 0 & 5 \end{bmatrix}$$

$$r_3 \leftarrow r_3 + 10r_2$$

$$\begin{bmatrix} 0 & 2 & 3 \\ 0 & 0 & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix}$$

$$r_2 \leftarrow 2r_2 \quad (\text{rescale})$$

$$\begin{bmatrix} 0 & 2 & 3 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$r_1 \leftarrow r_1 - 3r_2$$

$$\begin{bmatrix} 0 & 2 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$r_1 \leftarrow \frac{1}{2} r_1$$

$$\begin{array}{ccc} x_1 & x_2 & x_3 \\ \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \end{array}$$

reduced echelon form  
read off the solution

$$x_1 = \text{free}$$

$$x_2 = 0$$

$$x_3 = 0$$

$$x = \begin{bmatrix} x_1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} x_1$$

$$\text{Nul}(A - 1I) = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right\}$$

Eigenspace of the eigenvalue  $\lambda = 1$ .

For example  $v_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$  is an eigenvector with eigenvalue  $\lambda_1 = 1$

same vector ... eigenvector

$$\begin{bmatrix} 1 & 2 & 3 \\ 0 & 4 & 5 \\ 0 & 0 & 6 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = 1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

eigenvalue

$$\lambda = 4$$

$$A - \lambda I = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 4 & 5 \\ 0 & 0 & 6 \end{bmatrix} - 4 \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} -3 & 2 & 3 \\ 0 & 0 & 5 \\ 0 & 0 & 2 \end{bmatrix}$$

Now find the nullspace...

$$\begin{bmatrix} -3 & 2 & 3 \\ 0 & 0 & 5 \\ 0 & 0 & 2 \end{bmatrix}$$

$$r_3 \leftarrow r_3 - \frac{2}{5} r_2$$

$$r_1 \leftarrow r_1 - \frac{3}{5} r_2$$

$$\begin{bmatrix} -3 & 2 & 0 \\ 0 & 0 & 5 \\ 0 & 0 & 0 \end{bmatrix}$$

$$r_1 \leftarrow -\frac{1}{3} r_1$$

$$r_2 \leftarrow \frac{1}{5} r_2$$

reduced echelon form

$$\begin{array}{ccc} \text{P} & \text{F} & \text{P} \\ \left[ \begin{array}{ccc} 1 & -2/3 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{array} \right] \end{array}$$

Solve for pivots in terms of free variables

$$x_1 - \frac{2}{3}x_2 = 0$$

$$x_3 = 0$$

$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} \frac{2}{3}x_2 \\ x_2 \\ 0 \end{bmatrix} = \begin{bmatrix} 2/3 \\ 1 \\ 0 \end{bmatrix} x_2$$

$$\text{Nul}(A-4I) = \text{Span} \left\{ \begin{bmatrix} 2/3 \\ 1 \\ 0 \end{bmatrix} \right\} = \text{Span} \left\{ \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix} \right\}$$

both eigenvectors for  $\lambda=4$

might want a unit eigenvector.  
(rescale so norm is 1).

$\lambda=6$

$$A - \lambda I = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 4 & 5 \\ 0 & 0 & 6 \end{bmatrix} - 6 \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} -5 & 2 & 3 \\ 0 & -2 & 5 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} -5 & 2 & 3 \\ 0 & -2 & 5 \\ 0 & 0 & 0 \end{bmatrix}$$

$$r_1 \leftarrow r_1 + r_2$$

$$\begin{bmatrix} -5 & 0 & 8 \\ 0 & -2 & 5 \\ 0 & 0 & 0 \end{bmatrix}$$

$$r_1 \leftarrow -\frac{1}{5}r_1$$

$$r_2 \leftarrow -\frac{1}{2}r_2$$

reduced echelon form

$$\begin{bmatrix} 1 & 0 & -8/5 \\ 0 & 1 & -5/2 \\ 0 & 0 & 0 \end{bmatrix}$$

$$x_1 = \frac{8}{5}x_3$$

$$x_2 = \frac{5}{2}x_3$$

$$x_3 = x_3$$

$$\begin{aligned} \text{Nul}(A-1I) &= \text{Span} \left\{ \begin{bmatrix} 8/5 \\ 5/2 \\ 1 \end{bmatrix} \right\} \\ &= \text{Span} \left\{ \begin{bmatrix} 16 \\ 25 \\ 10 \end{bmatrix} \right\} \end{aligned}$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 0 & 4 & 5 \\ 0 & 0 & 6 \end{bmatrix} \begin{bmatrix} 16 \\ 25 \\ 10 \end{bmatrix} = \begin{bmatrix} 16 + 50 + 30 \\ 100 + 50 \\ 60 \end{bmatrix} = \begin{bmatrix} 96 \\ 150 \\ 60 \end{bmatrix} = 6 \begin{bmatrix} 16 \\ 25 \\ 10 \end{bmatrix}$$

an eigenvector

eigenvalue

$$\left( \lambda_1 = 1, v_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right) \text{ and } \left( \lambda_2 = 4, v_2 = \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix} \right) \text{ and } \left( \lambda_3 = 6, v_3 = \begin{bmatrix} 16 \\ 25 \\ 10 \end{bmatrix} \right)$$

Chapter 5.1  
Theorem 2

If  $v_1, \dots, v_r$  are eigenvectors that correspond to distinct eigenvalues  $\lambda_1, \dots, \lambda_r$  of an  $n \times n$  matrix  $A$ , then the set  $\{v_1, \dots, v_r\}$  is linearly independent.

read proof for next time

$$\beta = \{e_1, e_2, e_3\}$$

$$\mathcal{C} = \{v_1, v_2, v_3\}$$

$$\beta = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$$

$$\mathcal{C} = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix}, \begin{bmatrix} 16 \\ 25 \\ 10 \end{bmatrix} \right\}$$

Change of basis matrix

$$[\beta \leftarrow \mathcal{C}] = \begin{bmatrix} [v_1]_{\beta} & [v_2]_{\beta} & [v_3]_{\beta} \\ \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots \end{bmatrix} = \begin{bmatrix} v_1 & v_2 & v_3 \\ \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots \end{bmatrix} = \begin{bmatrix} 1 & 2 & 16 \\ 0 & 3 & 25 \\ 0 & 0 & 10 \end{bmatrix}$$

$$[\mathcal{C} \leftarrow \beta] = [\beta \leftarrow \mathcal{C}]^{-1} = \begin{bmatrix} 1 & 2 & 16 \\ 0 & 3 & 25 \\ 0 & 0 & 10 \end{bmatrix}^{-1}$$

Idea write the linear function represented by  $A$  in the basis  $\mathcal{C}$ .

$Ax$

$$x = [x]_{\beta} = [\beta \leftarrow e][x]_e$$

$$[Ax]_e = [e \leftarrow \beta][Ax]_{\beta} = [e \leftarrow \beta]Ax$$

$$= [e \leftarrow \beta]A[\beta \leftarrow e][x]_e$$

... this is the representation of  $A$   
in the  $e$  basis.