

Summary.

- Given a basis $\{u_1, u_2, \dots, u_p\} \subseteq \mathbb{R}^n$ for a subspace $W \subseteq \mathbb{R}^n$ the orthogonal projection $P: \mathbb{R}^n \rightarrow W$ is given
$$P = U(U^T U)^{-1} U^T$$

where $U = \begin{bmatrix} u_1 & u_2 & \dots & u_p \end{bmatrix}$.

- If basis is orthogonal $u_i \cdot u_j = \begin{cases} \|u_i\|^2 > 0 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$

Then $P = P_{u_1} + P_{u_2} + \dots + P_{u_p}$ where P_{u_i} is the projection onto the span $\{u_i\}$.

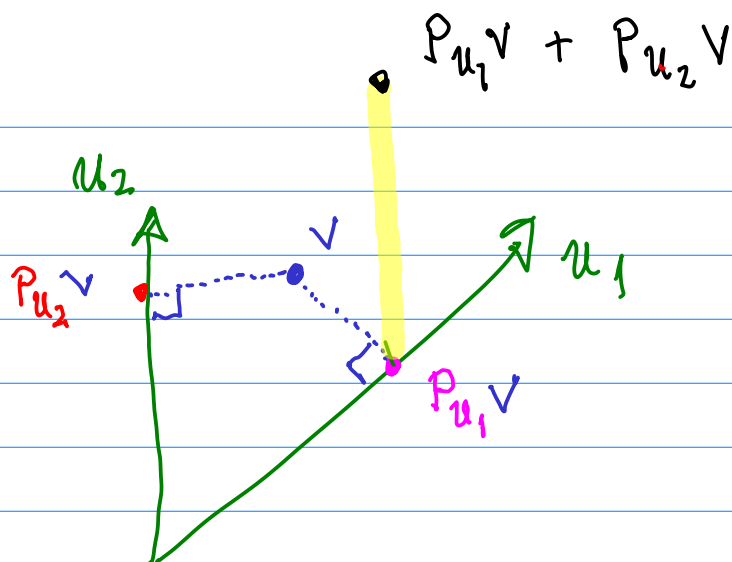
$$P_{u_i} v = \frac{u_i \cdot v}{\|u_i\|^2} u_i = \frac{u_i u_i^T}{\|u_i\|^2} v \quad P_{u_i} = \frac{u_i u_i^T}{\|u_i\|^2}$$

- If basis is orthonormal $u_i \cdot u_j = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$

Then $U^T U = I$ and $P = U U^T$

and $P_{u_i} v = (u_i \cdot v) u_i = u_i u_i^T v \quad P_{u_i} = u_i u_i^T$

Warning if $\{u_1, u_2, \dots, u_p\}$ is not orthogonal then
$$P \neq P_{u_1} + P_{u_2} + \dots + P_{u_p}$$



$P.v$ the the
projection onto
the page, then

$$Pv \neq P_{u_1}v + P_{u_2}v$$

Idea given any basis $\{u_1, u_2, \dots, u_p\}$ find an
orthogonal basis $\{v_1, v_2, \dots, v_p\}$ for the same subspace and
a orthonormal basis $\{q_1, q_2, \dots, q_n\}$ for the same subspace.

last step $q_1 = \frac{v_1}{\|v_1\|}, q_2 = \frac{v_2}{\|v_2\|}, \dots, q_p = \frac{v_p}{\|v_p\|}$

First step... find the v_i ... Gram-Schmidt algorithm.

Gaussian elimination

row operation

two triangular matrices

row operation for every equation
and every variable.

about n^2 row operations.

$n \cdot n^2$ total arithmetic operation

Gram-Schmidt

column operations

one orthogonal matrix
and one triangular.

make a projection for
each column

projections are matrix-vector
multiplication n^2
arithmetic operations.

$n \cdot n^2$ total arithmetic
operations.

also n square roots for
the norms...

Gram-Schmidt orthogonalization algorithm..

Given $\{u_1, \dots, u_p\}$ find $\{v_1, \dots, v_p\}$

$$v_1 = u_1$$

$$\text{span}\{v_1\} = \text{span}\{u_1\}$$

$$v_2 = u_2 - P_{v_1} u_2$$

nothing extra here.

$$\text{span}\{v_1, v_2\} = \text{span}\{u_1, u_2 - P_{v_1} u_2\} = \text{span}\left\{u_1, u_2 - \frac{v_1 \cdot u_2}{v_1 \cdot v_1} v_1\right\}$$

$\uparrow$ proj onto v_1

$$= \text{span}\{u_1, u_2\}$$

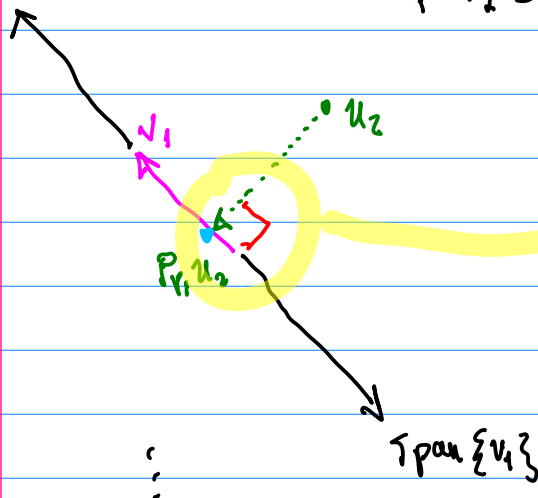
$$v_3 = u_3 - P_{v_1} u_3 - P_{v_2} u_3$$

this is the projection onto $\text{span}\{v_1, v_2\}$ because v_1 and v_2 are orthogonal.

$$v_1 \cdot v_2 = v_1 \cdot (u_2 - P_{v_1} u_2) = 0$$

closest point in v_1 to u_2
in span of v_1

since $P_{v_1} u_2$ is the orthogonal projection



$$v_p = u_p - P_{v_1} u_p - P_{v_2} u_p - \dots - P_{v_{p-1}} u_p$$

projection onto the span $\{v_1, \dots, v_{p-1}\}$.

thus $v_p \cdot v_i = 0$ for any $i = 1, 2, \dots, p-1$

What we just wrote out

Theorem 11
in section
6.4

The Gram-Schmidt Process

Given a basis $\{x_1, \dots, x_p\}$ for a nonzero subspace W of $\mathbb{R}^n$, define

$$v_1 = x_1$$

$$v_2 = x_2 - \frac{x_2 \cdot v_1}{v_1 \cdot v_1} v_1$$

$$v_3 = x_3 - \frac{x_3 \cdot v_1}{v_1 \cdot v_1} v_1 - \frac{x_3 \cdot v_2}{v_2 \cdot v_2} v_2$$

$\vdots$

$$v_p = x_p - \frac{x_p \cdot v_1}{v_1 \cdot v_1} v_1 - \frac{x_p \cdot v_2}{v_2 \cdot v_2} v_2 - \dots - \frac{x_p \cdot v_{p-1}}{v_{p-1} \cdot v_{p-1}} v_{p-1}$$

Then $\{v_1, \dots, v_p\}$ is an orthogonal basis for W . In addition

$$\text{Span}\{v_1, \dots, v_k\} = \text{Span}\{x_1, \dots, x_k\} \quad \text{for } 1 \leq k \leq p \quad (1)$$

Modify algorithm to create $q_i = \frac{v_i}{\|v_i\|} \dots$

$$v_1 = u_1$$

$$q_1 = \frac{v_1}{\|v_1\|}$$

$$v_2 = u_2 - (q_1 \cdot u_2) q_1$$

$$q_2 = \frac{v_2}{\|v_2\|}$$

$$v_3 = u_3 - (q_1 \cdot u_3) q_1 - (q_2 \cdot u_3) q_2$$

$$q_3 = \frac{v_3}{\|v_3\|}$$

$\vdots$

$$v_p = u_p - (q_1 \cdot u_p) q_1 - (q_2 \cdot u_p) q_2 - \dots - (q_{p-1} \cdot u_p) q_{p-1}$$

$$q_p = \frac{v_p}{\|v_p\|}$$

Then $\{q_1, q_2, \dots, q_p\}$ is an orthonormal basis. $\dots$

Write u_i 's in terms of q_i 's to find a matrix factorization given by this algorithm.

Assumption I know all the dot products, the norms and the q_i 's ... Now solve for the u_i 's

$$v_1 = u_1$$

$$q_1 = \frac{v_1}{\|v_1\|}$$

$$u_1 = v_1 = \|v_1\| q_1$$

$$v_1 = \|v_1\| q_1$$

$$v_2 = u_2 - (q_1 \cdot u_2) q_1$$

$$q_2 = \frac{v_2}{\|v_2\|}$$

$$u_2 = (q_1 \cdot u_2) q_1 + \|v_2\| q_2$$

$$v_3 = u_3 - (q_1 \cdot u_3) q_1 - (q_2 \cdot u_3) q_2$$

$$q_3 = \frac{v_3}{\|v_3\|}$$

$$u_3 = (q_1 \cdot u_3) q_1 + (q_2 \cdot u_3) q_2 + \|v_3\| q_3$$

$$v_p = u_p - (q_1 \cdot u_p) q_1 - (q_2 \cdot u_p) q_2 - \dots - (q_{p-1} \cdot u_p) q_{p-1}$$

$$q_p = \frac{v_p}{\|v_p\|}$$

$$u_p = (q_1 \cdot u_p) q_1 + (q_2 \cdot u_p) q_2 + \dots + (q_{p-1} \cdot u_p) q_{p-1} + \|v_p\| q_p$$

$$\begin{bmatrix} u_1 & u_2 & \dots & u_p \end{bmatrix} = \begin{bmatrix} q_1 & q_2 & \dots & q_p \end{bmatrix} \begin{bmatrix} \|v_1\| & q_1 \cdot u_2 & \dots & q_1 \cdot u_p \\ 0 & \|v_2\| & \dots & q_2 \cdot u_p \\ \vdots & 0 & \ddots & \vdots \\ 0 & 0 & \dots & \|v_p\| \end{bmatrix}$$

$U = Q R$

orthogonal