





looks like a fn def ~

↓ convert to expression to avoid Num type later

```

julia> gs="g(x,y)="*string(Symbolics.toexpr(gradf))
"g(x,y)=begin\n      \#= /x/float64/ejolson/.julia/packages
de.jl:685 =#\n      (SymbolicUtils.Code.create_array)(
(), Val{(2,)}(), (*)(0.02023809523809524, (+)((+)((+
)(5.46, (+)(-1, x)), (^)((+)((^)(" ... 1537 bytes ... "(-
+)(-3, y), 2)), 0.5449999999999999)), (/)((*)(7.28,
)(-3, x), 2), (^)((+)(-5, y), 2)), 0.5449999999999999
y)), (^)((+)((^)((+)(-5, x), 2), (^)((+)(-1, y), 2))
nd"

julia> eval(Meta.parse(gs))
g (generic function with 1 method)

```

← feed back in to Julia ...

```

julia> g(x,y) ← ∇z is the function.
2-element Vector{Num}:
 0.02023809523809524((5.46(-1 + x)) / (((-1 + x)^2 + (-5 + y)^2)^0.
999) + (5.46(-5 + x)) / (((-5 + x)^2 + (-1 + y)^2)^0.5449999999999
3 + x)) / (((-3 + x)^2 + (-5 + y)^2)^0.5449999999999999) + (2.73(-
5 + x)^2 + (-3 + y)^2)^0.5449999999999999) + (16.38(-1 + x)) / (((
1 + y)^2)^0.5449999999999999) + (5.46(-3 + x)) / (((-3 + x)^2 + (-
4999999999999999) + (7.28(-3 + x)) / (((-3 + x)^2 + (-1 + y)^2)^0.54
) + (7.28(-5 + x)) / (((-5 + x)^2 + (-5 + y)^2)^0.5449999999999999
+ x)) / (((-1 + x)^2 + (-3 + y)^2)^0.5449999999999999)
 0.02023809523809524((5.46(-5 + y)) / (((-1 + x)^2 + (-5 + y)^2)^0.
999) + (2.73(-3 + y)) / (((-5 + x)^2 + (-3 + y)^2)^0.5449999999999
1 + y)) / (((-3 + x)^2 + (-1 + y)^2)^0.5449999999999999) + (19.11(
-1 + x)^2 + (-3 + y)^2)^0.5449999999999999) + (7.28(-5 + y)) / (((
5 + y)^2)^0.5449999999999999) + (16.38(-1 + y)) / (((-1 + x)^2 + (
4499999999999999) + (5.46(-3 + y)) / (((-3 + x)^2 + (-3 + y)^2)^0.5
0) + (7.28(-5 + x)) / (((-3 + x)^2 + (-5 + y)^2)^0.5449999999999999

```

} solve this  
 $\nabla z = 0$

↙ gradient of z

```

gradf=Symbolics.gradient(fz(x,y),[x,y])
gs="g(x,y)="*string(Symbolics.toexpr(gradf))
eval(Meta.parse(gs))
jacg=Symbolics.jacobian(g(x,y),[x,y])
Dgs="Dg(x,y)="*string(Symbolics.toexpr(jacg))
eval(Meta.parse(Dgs))

```

← jacobian of the gradient...  
(same as hessian)

```

julia> xn=[2.0,3.0]
2-element Vector{Float64}:
 2.0
 3.0

julia> xn=xn-Dg(xn...)\g(xn...)
2-element Vector{Float64}:
 1.4711335100162801
 2.6821612659034932

```

... means feed the elements of the vector xn as the arguments xn[1], xn[2] into the functions Dg and g.

← improved approx...

again ... is called "split" operator and

iterates

```
julia> xn=xn-Dg(xn...)\g(xn...)
2-element Vector{Float64}:
 1.5639700775842522
 2.781032476478142

julia> xn=xn-Dg(xn...)\g(xn...)
2-element Vector{Float64}:
 1.6171501928978793
 2.7650714968565913

julia> xn=xn-Dg(xn...)\g(xn...)
2-element Vector{Float64}:
 1.6164879700559405
 2.76590753501586

julia> xn=xn-Dg(xn...)\g(xn...)
2-element Vector{Float64}:
 1.616487857748521
 2.765906920091334

julia> xn=xn-Dg(xn...)\g(xn...)
2-element Vector{Float64}:
 1.6164878577491917
 2.765906920090973
```

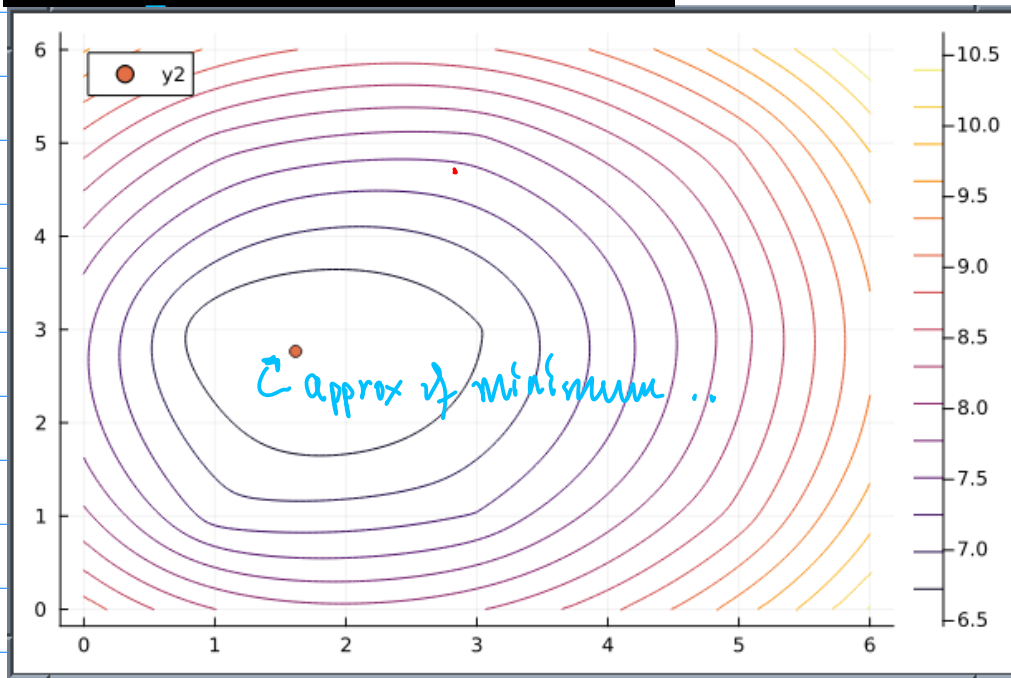
$Dg(xn...)$  means  $Dg(xn[1], xn[2])$

$g(xn...)$  means  $g(xn[1], xn[2])$

approx of minimum ..

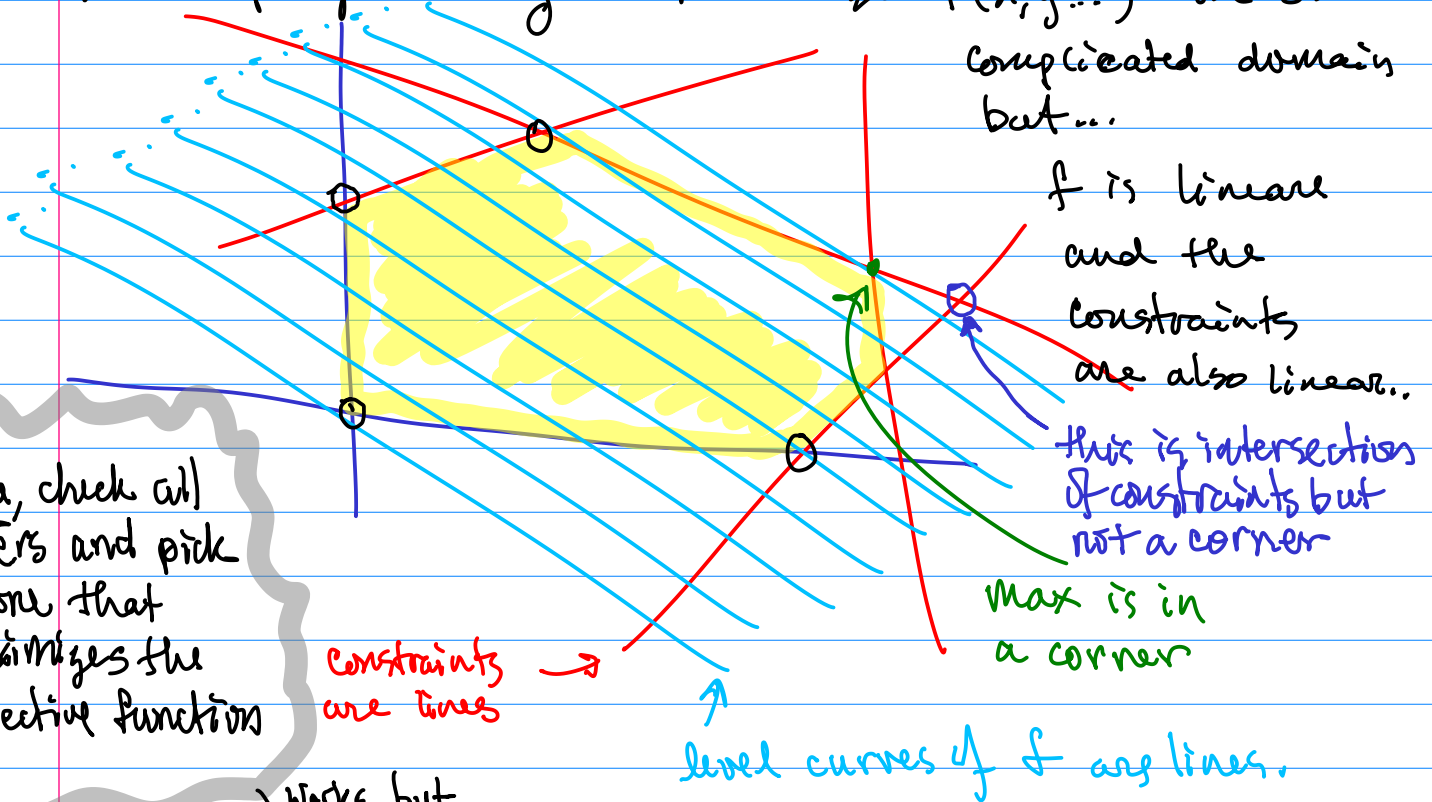
Plot the minimum we found on the contours ..

```
julia> scatter!((xn[1], xn[2]))
```



# Chapter 3.3 Linear Programming...

Linear programming: Maximize  $f(x, y, \dots)$  on a complicated domain but...

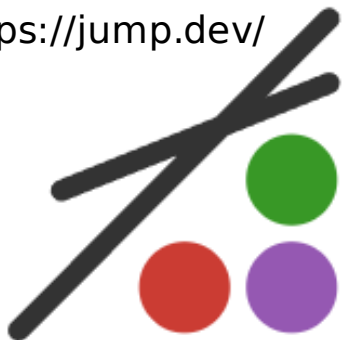


Idea, check all corners and pick the one that maximizes the objective function

works, but

When there are lots of variables the constraints are hyperplanes and there is a factorial number of corners to check... The idea is to move from corner to corner in a way that maximizes  $f$  and avoids checking all the corners...

<https://jump.dev/>



# JUMP

What is JuMP?