

$$\frac{dX}{dt} = F(X)$$

$$F(X) = F(x_1, x_2, x_3) = \begin{bmatrix} -\sigma x_1 + \sigma x_2 \\ -x_2 + r x_1 - x_1 x_3 \\ -b x_3 + x_1 x_2 \end{bmatrix}$$

$$X = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

$$F(x, y, z) = \begin{bmatrix} -\sigma x + \sigma y \\ -y + r x - x z \\ -b z + x y \end{bmatrix}$$

look for fixed points  $F(X) = 0$ . so

$$-\sigma x + \sigma y = 0 \quad x = y \quad \text{at any fixed point}$$

$$-y + r x - x z = 0 \quad \rightarrow \quad -x + r x - x z = 0$$

$$-b z + x y = 0$$

$$x(r-1-z) = 0$$

either  $x=0$  or  $r-1-z=0$

Case  $x=0$ .

then  $y=0$

$$-b z + x y = 0$$

$$-b z = 0 \quad \text{so } z = 0$$

one fixed point is  $(x, y, z) = (0, 0, 0)$

Case  $x \neq 0$

$$\text{then } r-1-z=0 \quad \text{so } z = r-1$$

$$-b z + x y = 0$$

$$-b(r-1) + x y = 0$$

also know  $x=y$

$$-b(r-1) + x^2 = 0 \quad x = \pm \sqrt{b(r-1)}$$

note if  $r < 1$  then  $x$  is imaginary and there are no such fixed points in the phase space. (real values of  $x, y, z$ ).

If  $r > 1$  then there are **additional** fixed points

$$(x, y, z) = (\sqrt{b(r-1)}, \sqrt{b(r-1)}, r-1)$$

and

$$(x, y, z) = (-\sqrt{b(r-1)}, -\sqrt{b(r-1)}, r-1)$$

Check **linear** stability of fixed points let  $X_0$  be fixed point then

$$F_L(x) = \overbrace{F(X_0)}^{=0} + DF(X_0)(x - X_0)$$

$$F_L(x) = A(x - X_0) \quad \text{where } A = DF(X_0).$$

Case  $X_0 = (0, 0, 0)$

$$F(x, y, z) = \begin{bmatrix} -\sigma x + \sigma y \\ -y + rx - xz \\ -bz + xy \end{bmatrix}$$

$$DF(x, y, z) = \begin{bmatrix} \frac{\partial F_1}{\partial x} & \frac{\partial F_1}{\partial y} & \frac{\partial F_1}{\partial z} \\ \frac{\partial F_2}{\partial x} & \frac{\partial F_2}{\partial y} & \frac{\partial F_2}{\partial z} \\ \frac{\partial F_3}{\partial x} & \frac{\partial F_3}{\partial y} & \frac{\partial F_3}{\partial z} \end{bmatrix} = \begin{bmatrix} -\sigma & \sigma & 0 \\ r - z & -1 & -x \\ y & x & -b \end{bmatrix}$$

$$A = DF(0, 0, 0) = \begin{bmatrix} -\sigma & \sigma & 0 \\ r & -1 & 0 \\ 0 & 0 & -b \end{bmatrix}$$

Check stability by finding the eigenvalues of  $A$  and checking whether the real parts of those eigenvalues are pos. or neg.

$$\chi(\lambda) = \det(A - \lambda I) = \det \begin{bmatrix} -\sigma - \lambda & \sigma & 0 \\ r & -1 - \lambda & 0 \\ 0 & 0 & -b - \lambda \end{bmatrix}$$

Expand determinant along the last column

$$\det \begin{bmatrix} -\sigma-\lambda & \sigma & 0 \\ r & -1-\lambda & 0 \\ 0 & 0 & -b-\lambda \end{bmatrix} = (-b-\lambda) \det \begin{bmatrix} -\sigma-\lambda & \sigma \\ r & -1-\lambda \end{bmatrix}$$

$$= -(b+\lambda) \left( (-\sigma-\lambda)(-1-\lambda) - r\sigma \right)$$

$$= -(b+\lambda) \left( (\sigma+\lambda)(1+\lambda) - r\sigma \right)$$

$$= \underbrace{-(b+\lambda)}_{\lambda_3} \left( \lambda^2 + (\sigma+1)\lambda + \sigma - r\sigma \right) = 0$$

one eigenvalue is  $\lambda_3 = -b$  this eigenvalue has neg. real part assuming  $b > 0$ .

other eigenvalues are roots of  $\lambda^2 + (\sigma+1)\lambda - (r-1)\sigma$

$$\alpha = 1 \quad \beta = \sigma + 1 \quad \gamma = -(r-1)\sigma$$

$$\lambda_{1,2} = \frac{-\beta \pm \sqrt{\beta^2 - 4\alpha\gamma}}{2\alpha} = \frac{-(\sigma+1) \pm \sqrt{(\sigma+1)^2 + 4(r-1)\sigma}}{2}$$

Standard values of  $\sigma = 10$  and  $b = 8/3$  but leave  $r$ .

$$\lambda_{1,2} = \frac{-(10+1) \pm \sqrt{(10+1)^2 + 4(r-1)10}}{2} = \frac{-11 \pm \sqrt{81+40r}}{2}$$

plus is more likely positive

$$(10+1)^2 + 4(r-1)10 = 11^2 - 40 + 40r = 121 - 40 + 40r = 81 + 40r$$

Stability requires  $-11 + \sqrt{81+40r} < 0$

$$\sqrt{81+40r} < 11 \quad 81+40r < 121 \quad 40r < 40 \quad r < 1.$$

If  $r > 1$  then the fixed point at  $(0,0,0)$  is unstable.  
(and there are two other fixed points)

If  $r < 1$  then the fixed point at  $(0,0,0)$  is stable  
(and that's the only fixed point)