

The QR decomposition of a matrix

$A \in \mathbb{R}^{m \times n}$  then  $A = QR$  where  $Q^T Q = I$   
and  $R$  is upper triangular.

The algorithm to find QR in an introductory linear algebra class is called Gram-Schmidt.

$$A = QR$$

$m \times n$     $m \times ?$     $? \times n$

$Q$

these two question marks have to be the same number... but what?

Two kinds of QR factorizations

① Full QR factorization.  $\begin{cases} Q \text{ is square} \\ R \text{ is not} \end{cases}$

② Reduced QR factorization.  $\begin{cases} R \text{ is square} \\ Q \text{ is not} \end{cases}$  ← The reduced comes from Gram-Schmidt naturally.

What's the difference? The dimensions of  $Q$  and  $R$ ...

Reduced QR decomposition:

$$A \in \mathbb{R}^{m \times n}$$

$$m \geq n$$

well determined  $m = n$   
over determined  $m > n$ .

$$A = QR \quad \leftarrow R \text{ is square...}$$

$m \times n$     $m \times n$     $n \times n$

Gram-Schmidt Algorithm.

$$A = \left[ \begin{array}{c|c|c} u_1 & u_2 & \dots & u_n \end{array} \right] \text{ where } u_j \in \mathbb{R}^m \text{ for } j=1, \dots, n$$

Use column operations to factor A:

Case  $n=3$

$$v_1 = u_1$$

$$q_1 = \frac{v_1}{\|v_1\|}$$

$$v_2 = u_2 - (q_1 \cdot u_2) q_1$$

$$q_2 = \frac{v_2}{\|v_2\|} \quad v_2 = \|v_2\| q_2$$

$$u_2 = v_2 + (q_1 \cdot u_2) q_1 = \|v_2\| q_2 + (q_1 \cdot u_2) q_1$$

$$v_3 = u_3 - (q_1 \cdot u_3) q_1 - (q_2 \cdot u_3) q_2$$

$$q_3 = \frac{v_3}{\|v_3\|} \quad v_3 = \|v_3\| q_3$$

$$u_3 = v_3 + (q_1 \cdot u_3) q_1 + (q_2 \cdot u_3) q_2$$

$$= \|v_3\| q_3 + (q_1 \cdot u_3) q_1 + (q_2 \cdot u_3) q_2$$

$$Q = \begin{bmatrix} | & | & | \\ q_1 & q_2 & q_3 \\ | & | & | \end{bmatrix}$$

$$R = \begin{bmatrix} \|v_1\| & q_1 \cdot u_2 & q_1 \cdot u_3 \\ 0 & \|v_2\| & q_2 \cdot u_3 \\ 0 & 0 & \|v_3\| \end{bmatrix}$$

Note this algorithm focuses on R.

Why... we do column operations and R stores them.

$$QR = \begin{bmatrix} \|v_1\| q_1 & (q_1 \cdot u_2) q_1 + \|v_2\| q_2 & (q_1 \cdot u_3) q_1 + (q_2 \cdot u_3) q_2 + \|v_3\| q_3 \\ | & | & | \end{bmatrix}$$

$$= \begin{bmatrix} | & | & | \\ u_1 & u_2 & u_3 \\ | & | & | \end{bmatrix} = A$$

For arbitrary  $n$

$$v_1 = u_1$$

$$q_1 = \frac{v_1}{\|v_1\|}$$

$$v_2 = u_2 - (q_1 \cdot u_2) q_1$$

$$q_2 = \frac{v_2}{\|v_2\|}$$

$$v_3 = u_3 - (q_1 \cdot u_3) q_1 - (q_2 \cdot u_3) q_2$$

$$q_3 = \frac{v_3}{\|v_3\|}$$

$$v_k = u_k - \sum_{l=1}^{k-1} (q_l \cdot u_k) q_l$$

$$q_k = \frac{v_k}{\|v_k\|}$$

for  $k=4, 5, \dots, n$ .

The Gram-Schmidt Focuses on making  $R$  and  
Gets  $Q$  as a result:

Is this  $Q^T Q = I$  true?

↑ rounding errors mess this  
orthogonality up..

Householder focuses on ensuring  $Q^T Q = I$  and  
gets  $R$  as a result. Interestingly there are  
choices that can be made that will further  
reduce rounding error when using Householder.