

skip ...

- ✓ 1. All the eigenvalues λ are real.
- ✓ 2. There exist an infinite number of eigenvalues:

$$\lambda_1 < \lambda_2 < \dots < \lambda_n < \lambda_{n+1} < \dots$$
 a. There is a smallest eigenvalue, usually denoted λ_1 .
 b. There is not a largest eigenvalue and $\lambda_n \rightarrow \infty$ as $n \rightarrow \infty$.

also true for symmetric matrices

- ✓ 3. Corresponding to each eigenvalue λ_n , there is an eigenfunction, denoted $\phi_n(x)$ (which is unique to within an arbitrary multiplicative constant). $\phi_n(x)$ has exactly $n - 1$ zeros for $a < x < b$.

difficult ...

4. The eigenfunctions $\phi_n(x)$ form a "complete" set, meaning that any piecewise smooth function $f(x)$ can be represented by a generalized Fourier series of the eigenfunctions:

$$f(x) \sim \sum_{n=1}^{\infty} a_n \phi_n(x).$$

Furthermore, this infinite series converges to $[f(x+) + f(x-)]/2$ for $a < x < b$ (if the coefficients a_n are properly chosen).

also true for symmetric matrices. means there is an orthogonal basis of eigenvectors or functions...

- ✓ 5. Eigenfunctions belonging to different eigenvalues are orthogonal relative to the weight function $\sigma(x)$. In other words,

$$\int_a^b \phi_n(x) \phi_m(x) \sigma(x) dx = 0 \quad \text{if } \lambda_n \neq \lambda_m.$$

spectral theorem for self adjoint operators (or matrices).

easy ...

6. Any eigenvalue can be related to its eigenfunction by the Rayleigh quotient:

$$\lambda = \frac{-p\phi \, d\phi/dx|_a^b + \int_a^b [p(d\phi/dx)^2 - q\phi^2] dx}{\int_a^b \phi^2 \sigma dx},$$

also defined for matrices...

where the boundary conditions may somewhat simplify this expression.

⑥ Consider matrix eigenvalue - eigenvector problem:

Math 330: $Ax = \lambda x$

used determinants to eliminate x from the equation:

$$\det(A - \lambda I) = 0$$

solve for λ . Now that you know λ plug it back in and solve for x

$$x \in \text{Null}(A - \lambda I) \setminus \{0\}.$$

where λ is the eigenvalue.

What if we somehow knew x . (how to find λ):

• Plug λ in and solve for x .

• It does happen in numerical linear algebra that some algorithm finds the x first. Then we need to find λ .

• From observations, one might just see an eigenfunction directly...

$$u(x,t) = \sum_{n=0}^{\infty} A_n \cos\left(\frac{n\pi x}{L}\right) e^{-k\left(\frac{n\pi}{L}\right)^2 t}$$

for example as $t \rightarrow \infty$ the solution looks like the leading term

$$u(x,t) \sim A_1 \cos\left(\frac{\pi x}{L}\right) e^{-k\left(\frac{\pi}{L}\right)^2 t}$$

eigenfunction...

linear algebra:

$$Ax = \lambda x$$

view as least squares optimization

solve for λ

idea ... use the inner product

$$Ax \cdot x = \lambda x \cdot x$$

is just a number, $x \cdot x > 0$ since by definition $x \neq 0$.

$$\lambda = \frac{Ax \cdot x}{x \cdot x}$$

solve for λ .

$Ax = \lambda x$ } there are n equations, $x \in \mathbb{R}^n$
 λ unknown

find λ that minimizes $\|Ax - \lambda x\|$.

rewrite so it looks like a least squares problem

$$Ax = \lambda x$$

$$x\lambda = \underbrace{Ax}_b$$

$$Ax = b$$

Find x to minimize $Ax = b$
solve

$$A^T A x = A^T b$$

normal equations...

blue variables are different than the black variables

$$A^T A x = A^T b$$

$$x^T x \lambda = x^T A x$$

$$x \cdot x \lambda = x \cdot Ax = Ax \cdot x$$

$$\lambda = \frac{Ax \cdot x}{x \cdot x} \quad \text{least squares solution for } \lambda.$$

Note the least squares solution is the exact solution if there actually is a solution.

This means $\min \{ \|Ax - \lambda x\| : \lambda \in \mathbb{R} \} = 0$

So λ is the exact solution and $Ax = \lambda x \dots$
eigenvalue...

Now translate all of this to differential operators and eigenfunctions...

$$L(\phi) + \lambda \sigma(x)\phi = 0,$$

Not only L is self adjoint but it's a Sturm-Liouville operator...

$$L(y) \equiv \frac{d}{dx} \left[p(x) \frac{dy}{dx} \right] + q(x)y.$$

Given ϕ solve for λ . Take inner products

$$(u, v) = \int_a^b u(x)v(x)dx \quad \text{means ...} = u \cdot v$$

$$(L(\phi), \phi) + (\lambda \sigma \phi, \phi) = 0$$

just a number...

$$(L(\phi), \phi) + \lambda (\sigma \phi, \phi) = 0$$

solve for λ

$$\lambda = \frac{-(L(\phi), \phi)}{(\sigma \phi, \phi)}$$

Raleigh
quotient
for λ

$$L(y) \equiv \frac{d}{dx} \left[p(x) \frac{dy}{dx} \right] + q(x)y.$$

Now simplify this

$$-(L\phi, \phi) = -\left(\frac{d}{dx}(p\phi') + q\phi, \phi \right)$$

$$= -\int_a^b \left(\frac{d}{dx}(p\phi') + q\phi \right) \phi \, dx$$

$$= -\int_a^b \left[\frac{d}{dx}(p\phi') \right] \phi \, dx - \int_a^b q\phi^2 \, dx$$

$$-\int_a^b \left[\frac{d}{dx}(p\phi') \right] \phi \, dx = -\left(uv \Big|_a^b - \int_a^b v \, du \right)$$

$$u = \phi$$

$$du = \phi' \, dx$$

$$dv = \left[\frac{d}{dx}(p\phi') \right] dx$$

$$v = \int dv = \left[\frac{d}{dx}(p\phi') \right] dx = p\phi'$$

fund theorem
of Calculus

$$-\int_a^b \left[\frac{d}{dx}(p\phi') \right] \phi \, dx = -p\phi\phi' \Big|_a^b + \int_a^b p(\phi')^2 \, dx$$

Therefore

$$\lambda = \frac{-(L\phi, \phi)}{(\sigma\phi, \phi)} \approx \frac{-p\phi\phi' \Big|_a^b + \int_a^b p(\phi')^2 \, dx - \int_a^b q\phi^2 \, dx}{\int_a^b \sigma\phi^2 \, dx}$$

is quotient

$$\lambda = \frac{-p\phi \, d\phi/dx \Big|_a^b + \int_a^b [p(d\phi/dx)^2 - q\phi^2] \, dx}{\int_a^b \phi^2 \sigma \, dx}$$

zero by boundary conditions...

might be negative... unless $q < 0$ then it's positive...

positive

The reason integration by parts is useful is because

$$\int_a^b p(x)(\phi'(x))^2 dx \geq 0 \quad \text{since } (\phi')^2 \geq 0$$

and in many applications $p > 0$,

For example

$$c(x)p(x) \frac{\partial u}{\partial t} = \frac{\partial}{\partial x} \left(k_0(x) \frac{\partial u}{\partial x} \right) + Q(x)$$

k_0 plays the role of $p(x)$ and this is positive

There's a homework problem where you might want to use the Rayleigh quotient to determine the sign of λ .

↓ This one...

5.3.8. Show that $\lambda \geq 0$ for the eigenvalue problem

$$\frac{d^2 \phi}{dx^2} + (\lambda - x^2)\phi = 0 \quad \text{with} \quad \frac{d\phi}{dx}(0) = 0, \quad \frac{d\phi}{dx}(1) = 0.$$

Is $\lambda = 0$ an eigenvalue?

Next time...

5.4 WORKED EXAMPLE: HEAT FLOW IN A NONUNIFORM ROD WITHOUT SOURCES

In this section we illustrate the application to partial differential equations of some of